



RICE UNIVERSITY

# **Week-2: Pytorch for Computer Vision**

# Motivation: Why Image Processing and Analysis?

## Classification



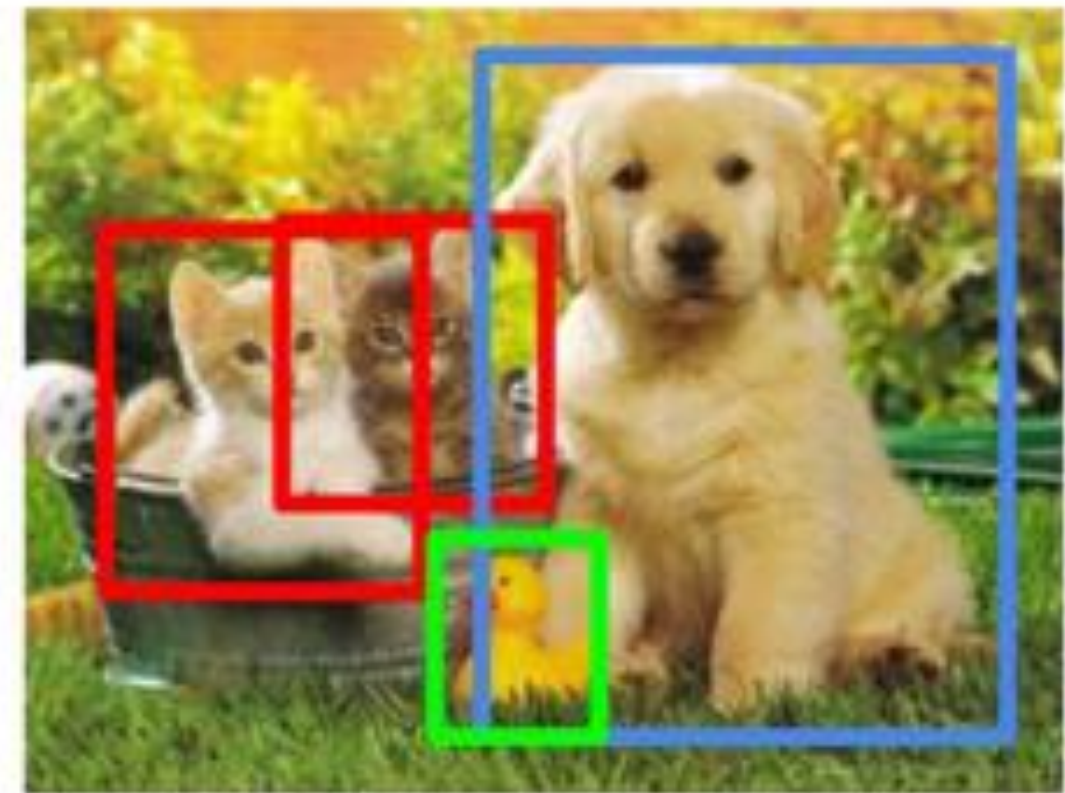
CAT

## Classification + Localization



CAT

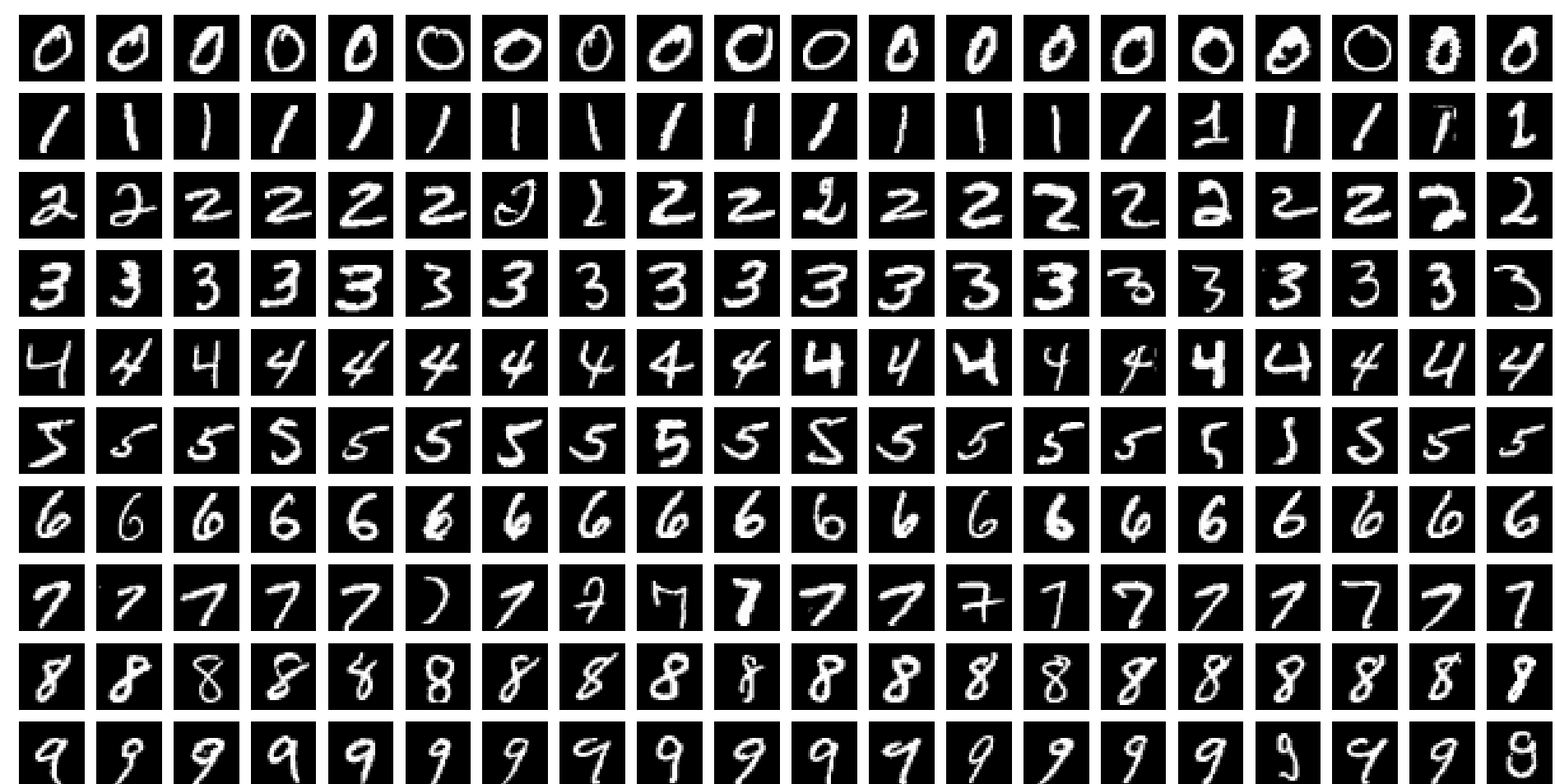
## Object Detection



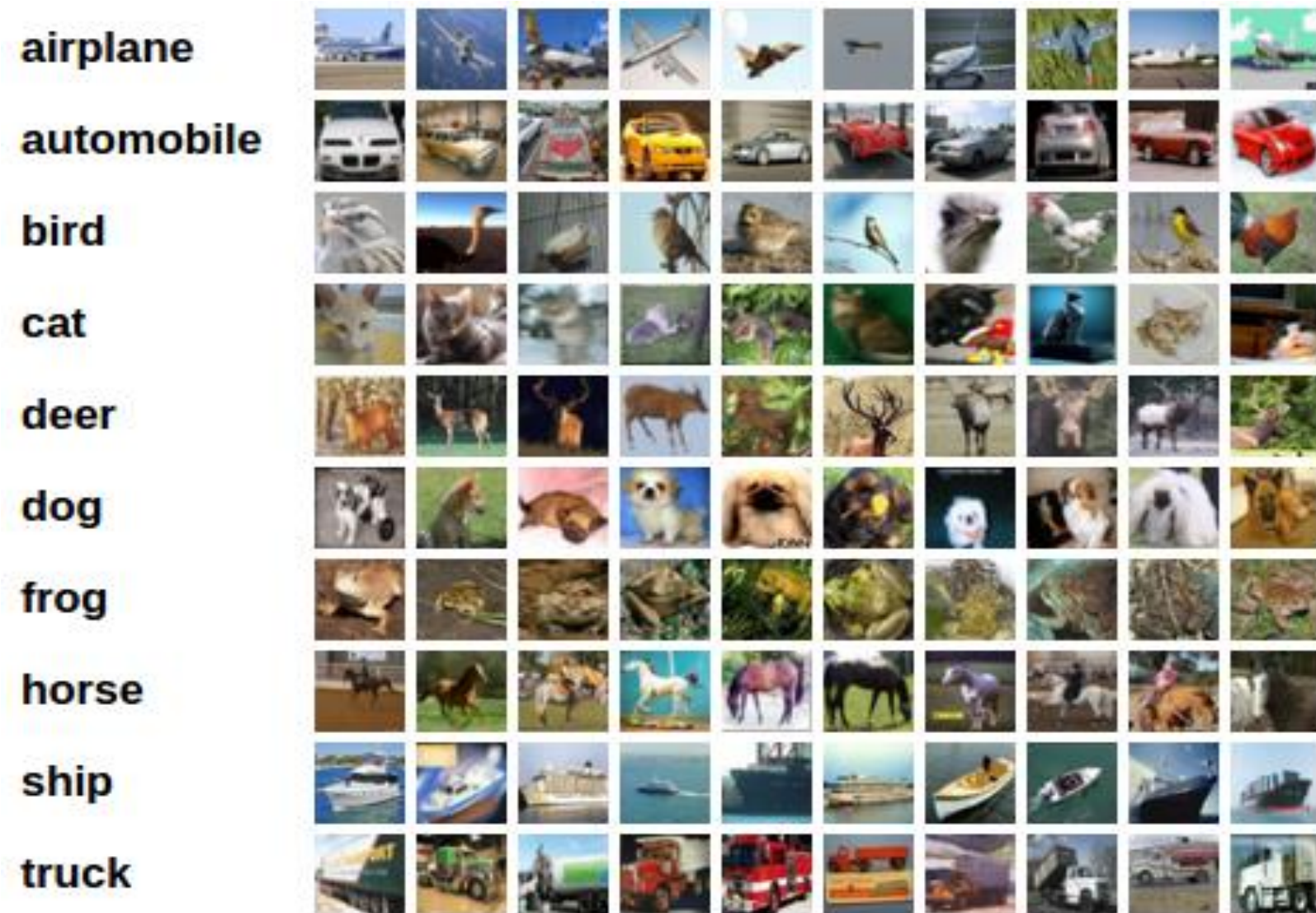
CAT, DOG, DUCK

# Image Datasets -- **MNIST**

- Handwritten digit dataset introduced by LeCun et al., 1998
- 70,000 grayscale images (28×28), digits 0–9
- 60K training / 10K test split
- Simple, lightweight benchmark for image classification



# Image Datasets -- **Cifar-10**



- Classic dataset introduced by Krizhevsky et al., 2009
- 60,000 color images (32×32), 10 object classes
- 50K training / 10K test split
- Compact, runs fast on CPU/GPU hardware

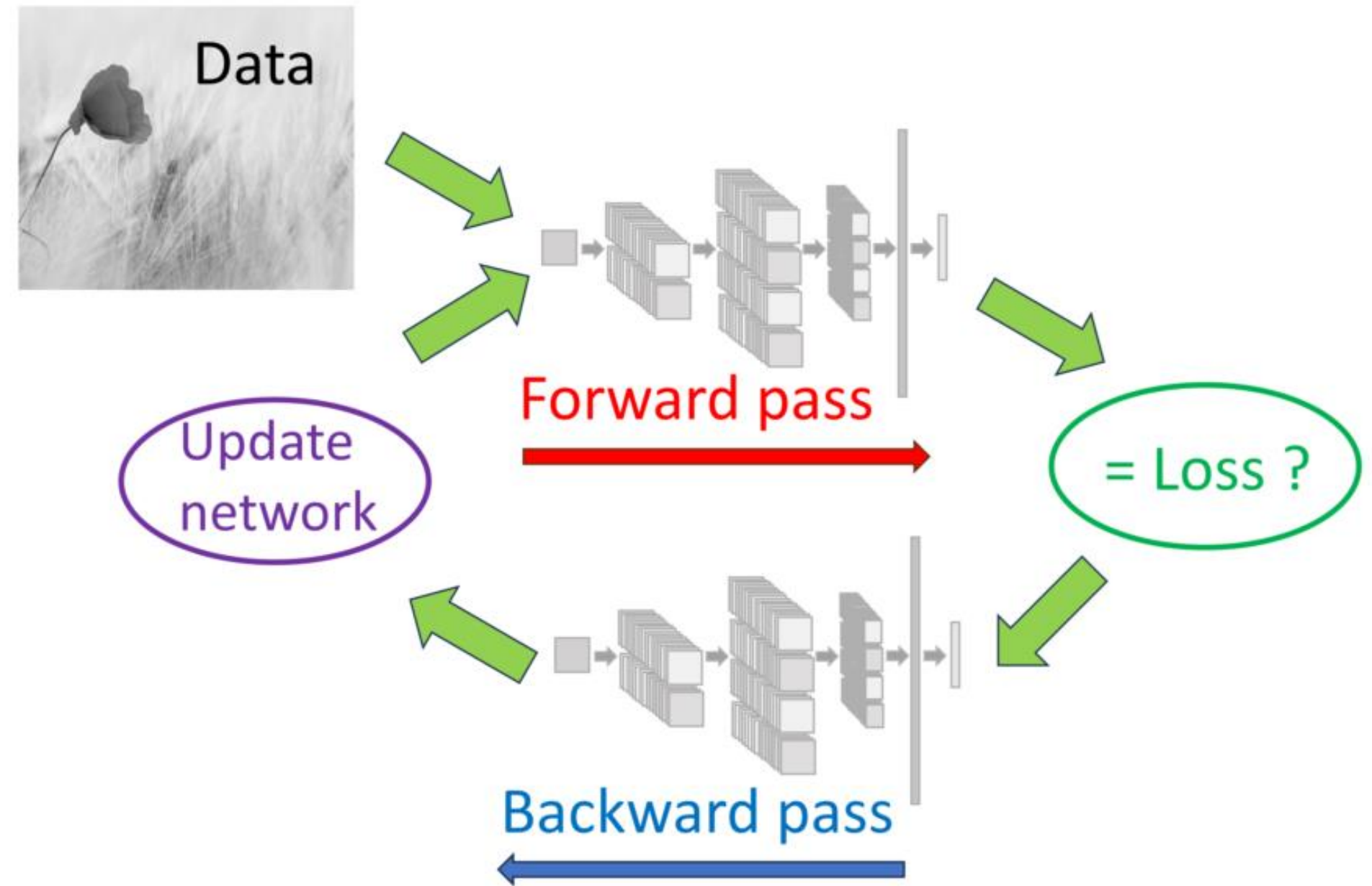
# Image Datasets -- **ImageNet**

- Large-scale visual dataset introduced by Deng et al., 2009
- Over 14 million labeled images, 21K+ object categories.
- Standard subset: 1.28M training / 50K validation images (1000 classes).
- High-resolution images (varied sizes), challenging benchmark for deep CNNs.

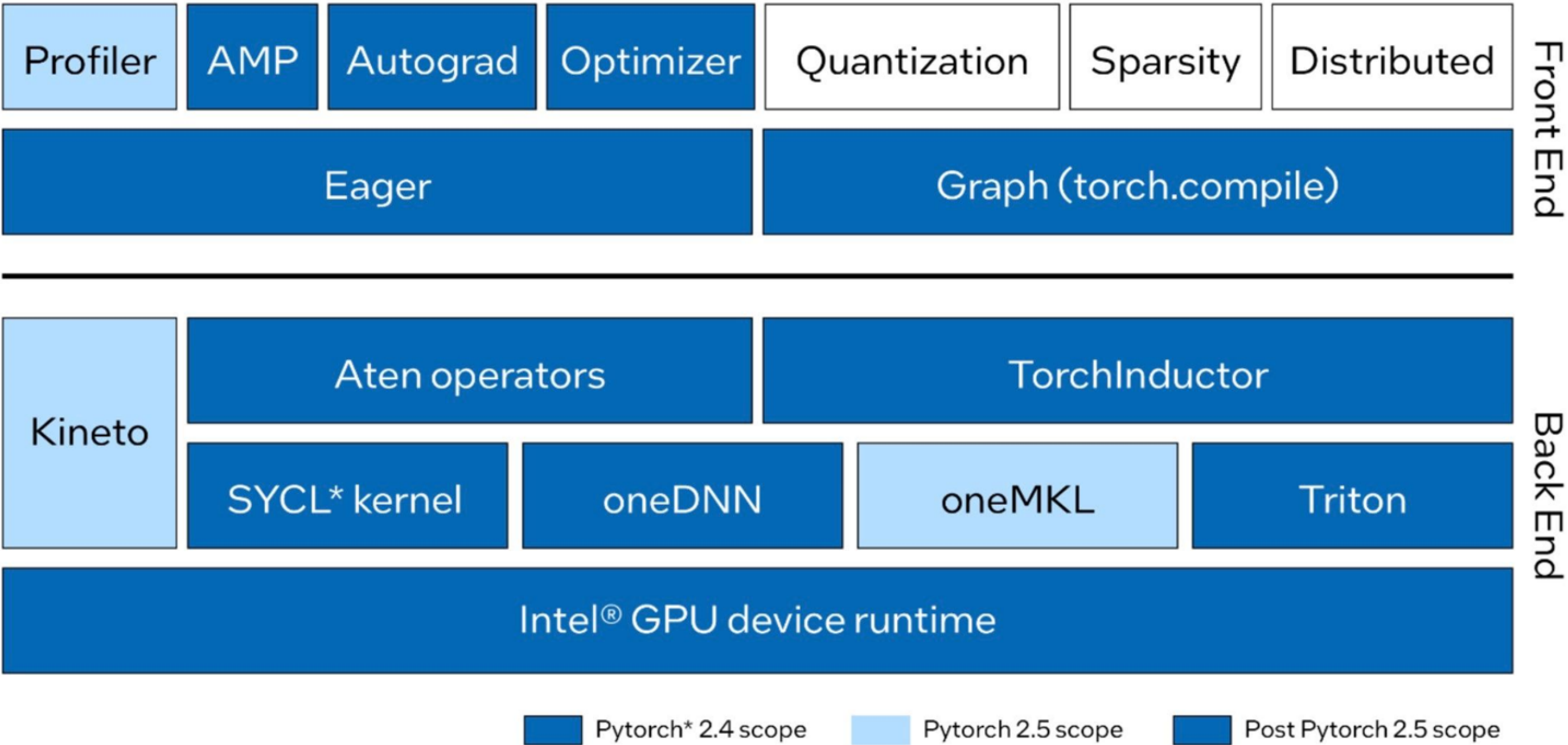


# Training Loop Essentials

- Move data to device (CPU/GPU)
- Forward pass → compute predictions
- Compute loss → backward() → update weights
- Repeat for multiple epochs



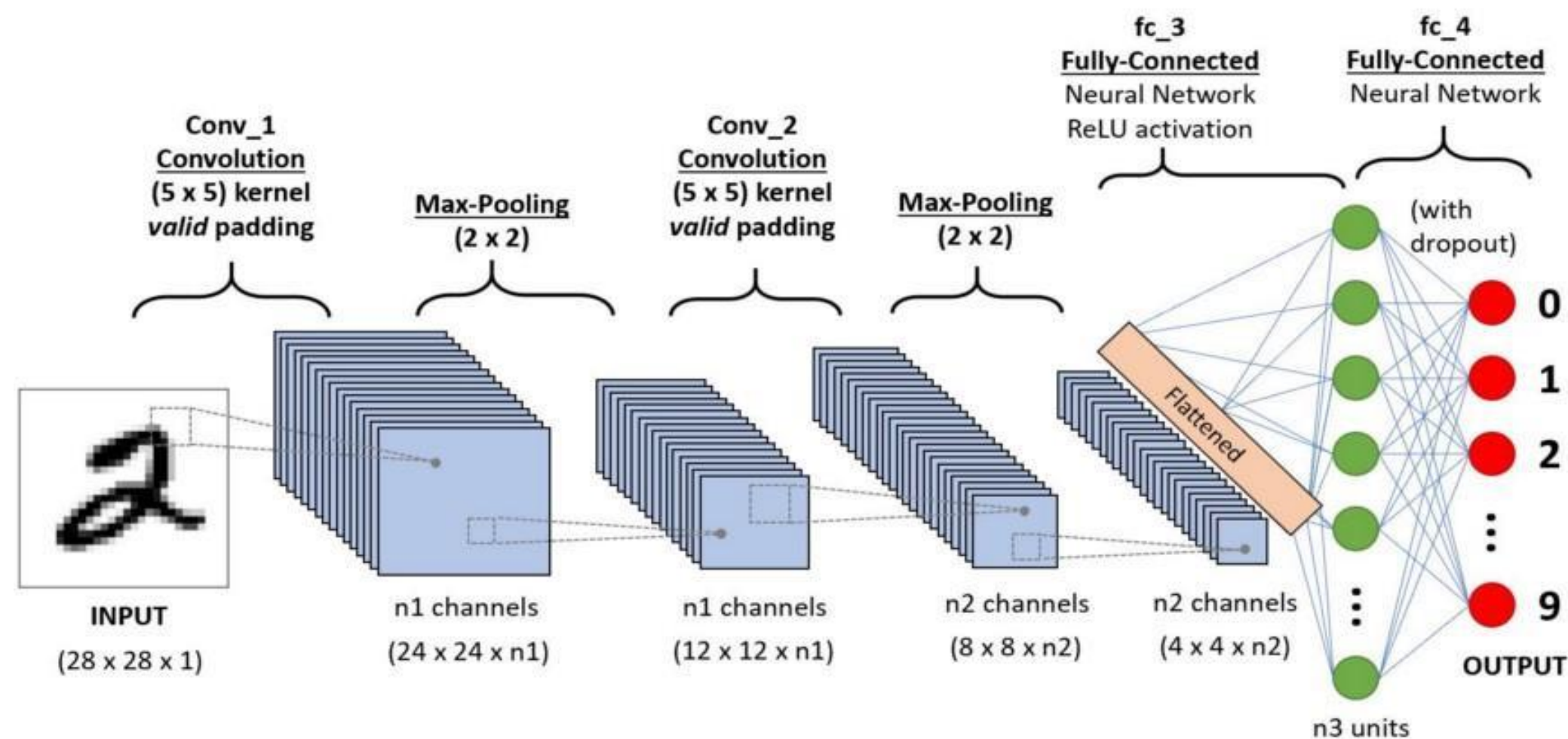
# PyTorch and Deep Learning Ecosystem



oneDNN stands for oneAPI Deep Neural Network Library and oneMKL stands for oneAPI Math Kernel Library.

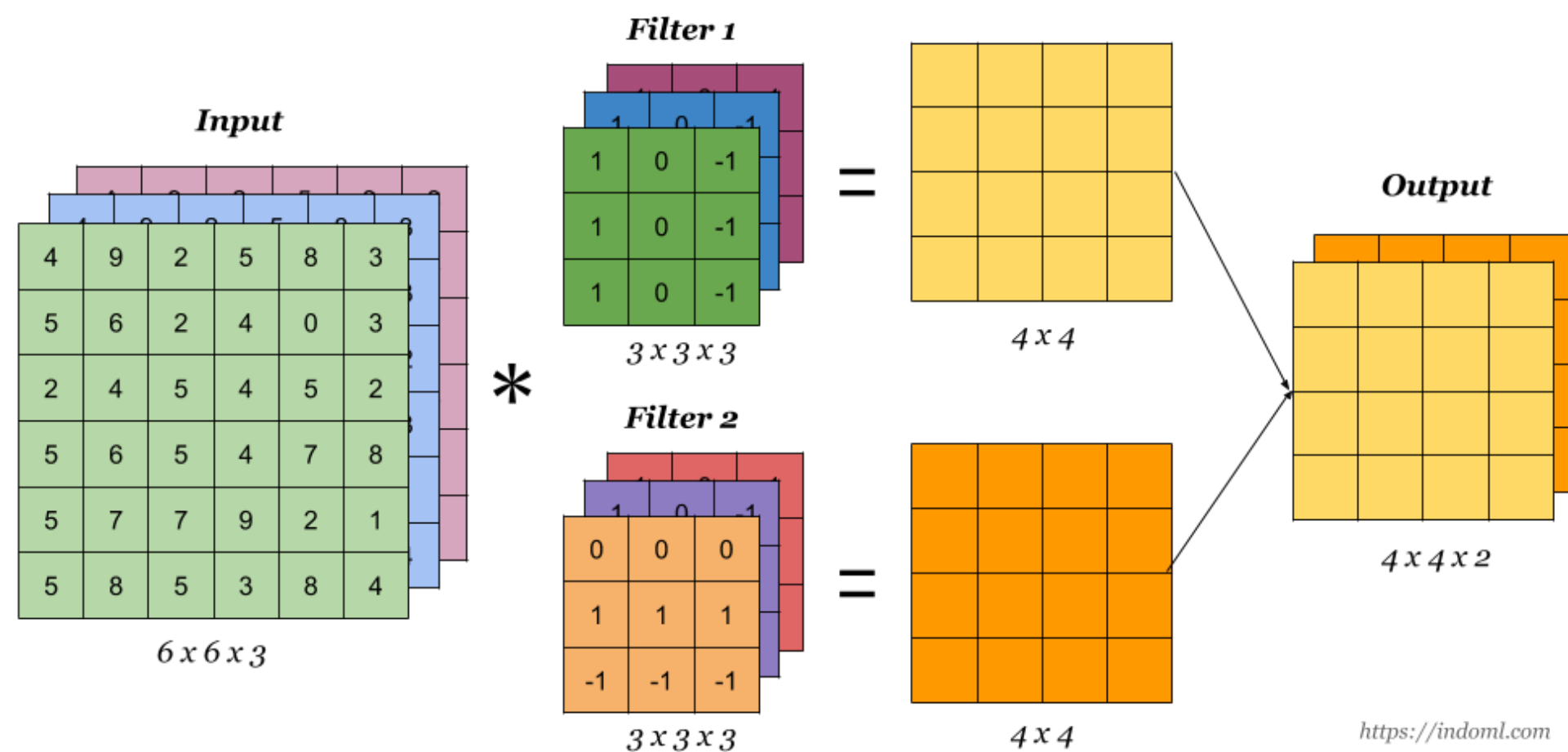
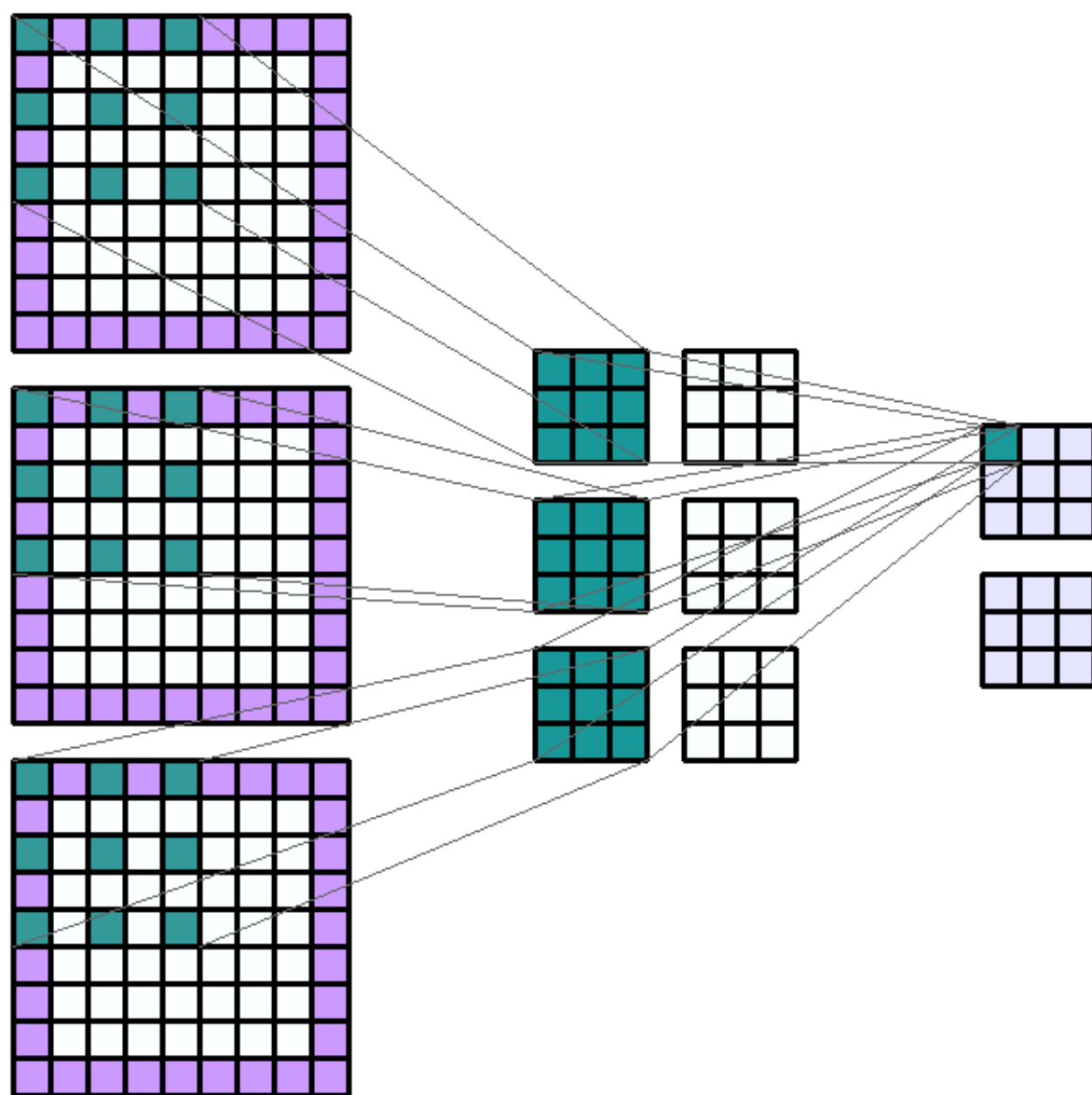
# Common Operators in CIFAR-10 Model

- Conv2d: extracts spatial features
- ReLU: adds nonlinearity
- MaxPool2d: downsampling
- Linear: fully connected layer
- CrossEntropyLoss: combines Softmax + log loss



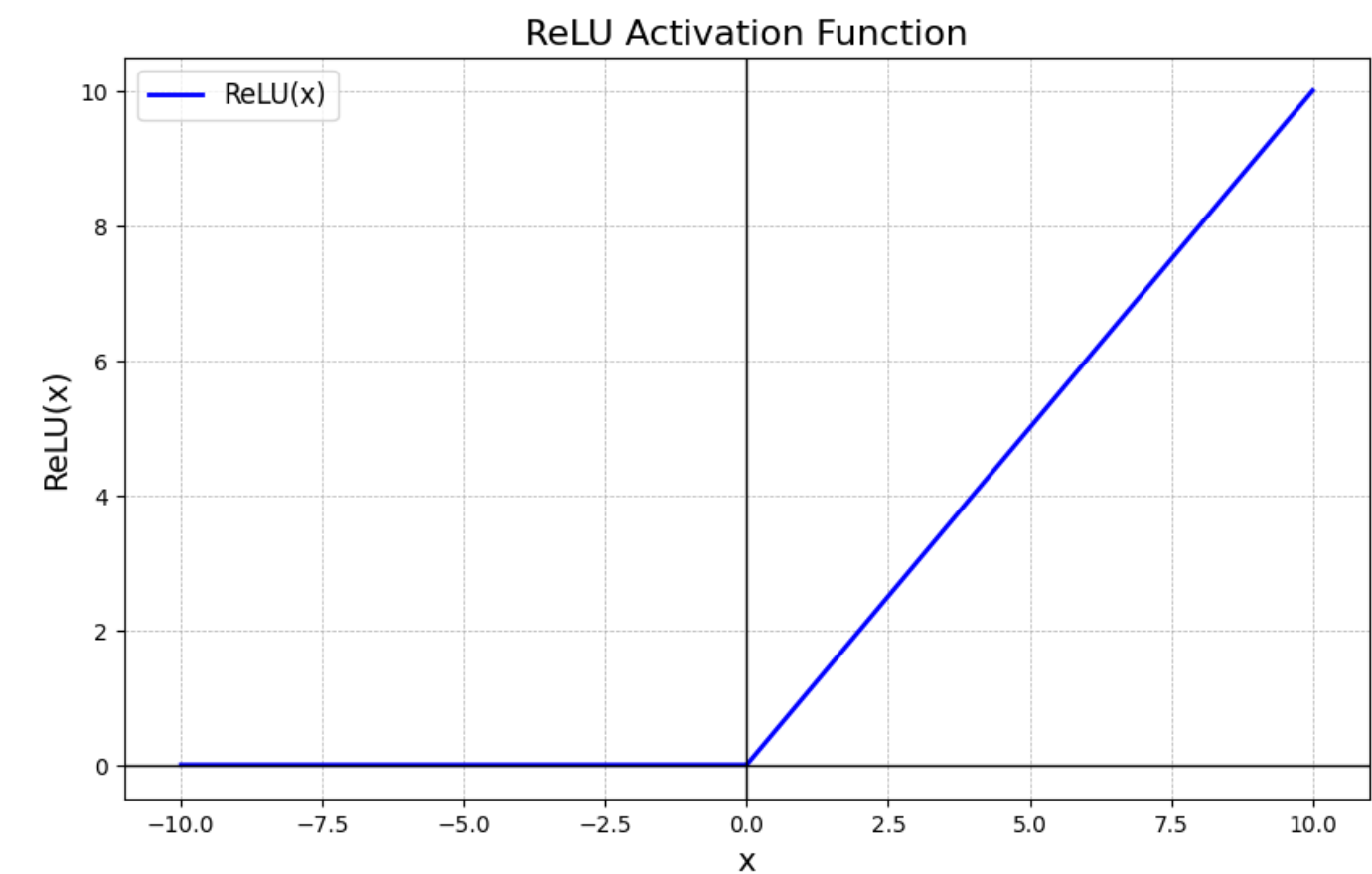
# Common Operators in CIFAR-10 Model

- **Conv2d: extracts spatial features**



# Common Operators in CIFAR-10 Model

- Conv2d: extracts spatial features
- **ReLU: adds nonlinearity**



Filter 1 Feature Map

|    |    |    |    |
|----|----|----|----|
| 9  | 3  | 5  | -8 |
| -6 | 2  | -3 | 1  |
| 1  | 3  | 4  | 1  |
| 3  | -4 | 5  | 1  |

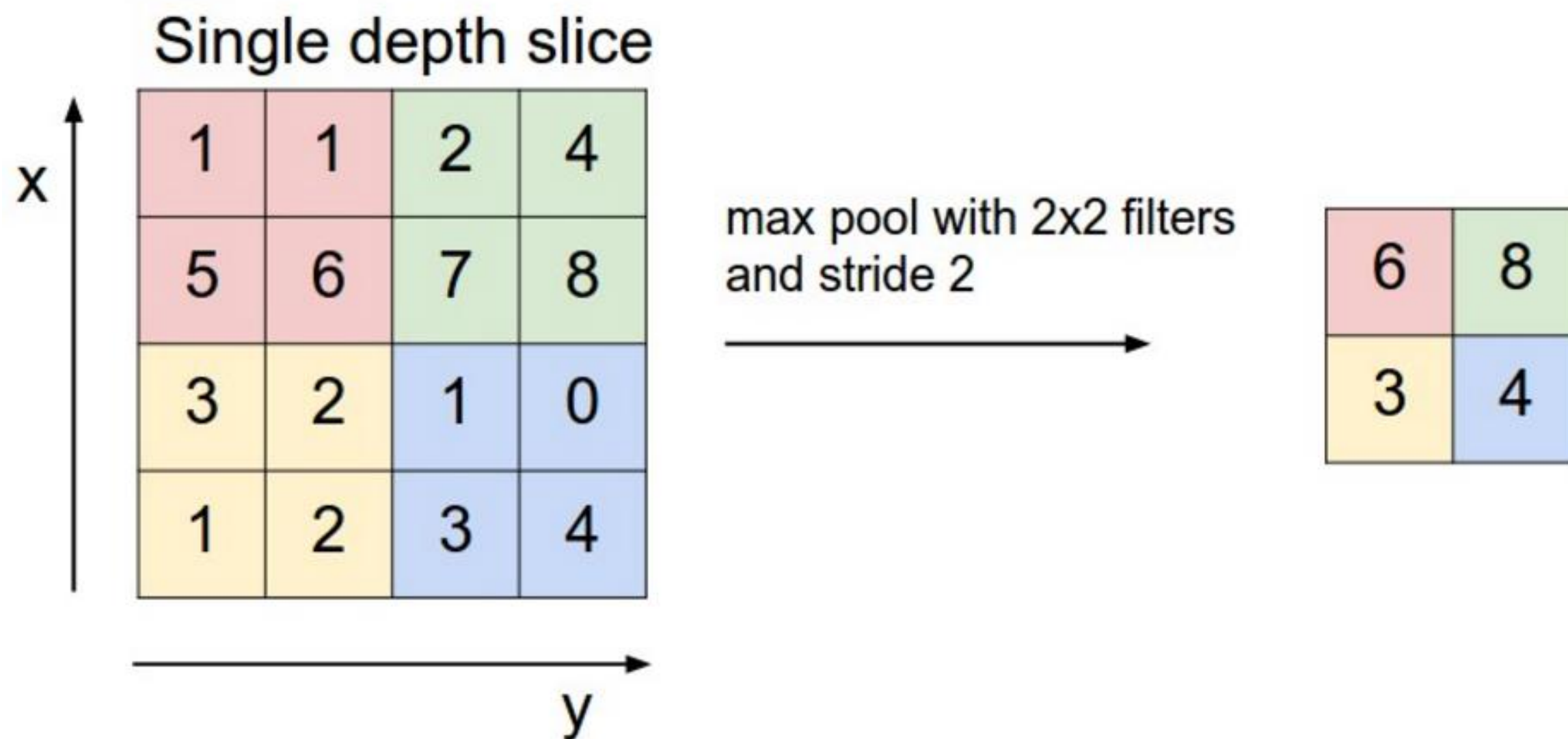
ReLU Layer



|   |   |   |   |
|---|---|---|---|
| 9 | 3 | 5 | 0 |
| 0 | 2 | 0 | 1 |
| 1 | 3 | 4 | 1 |
| 3 | 0 | 5 | 1 |

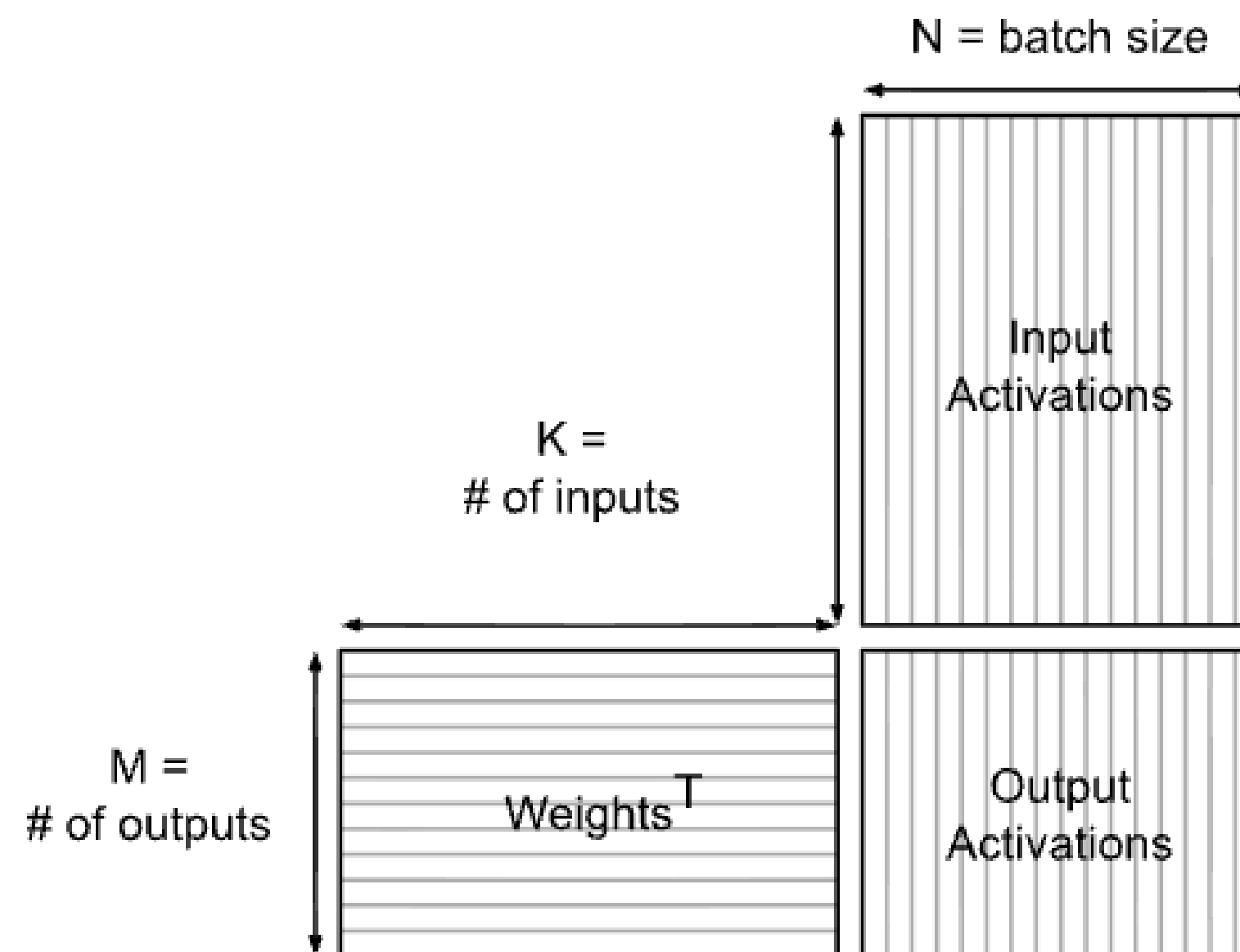
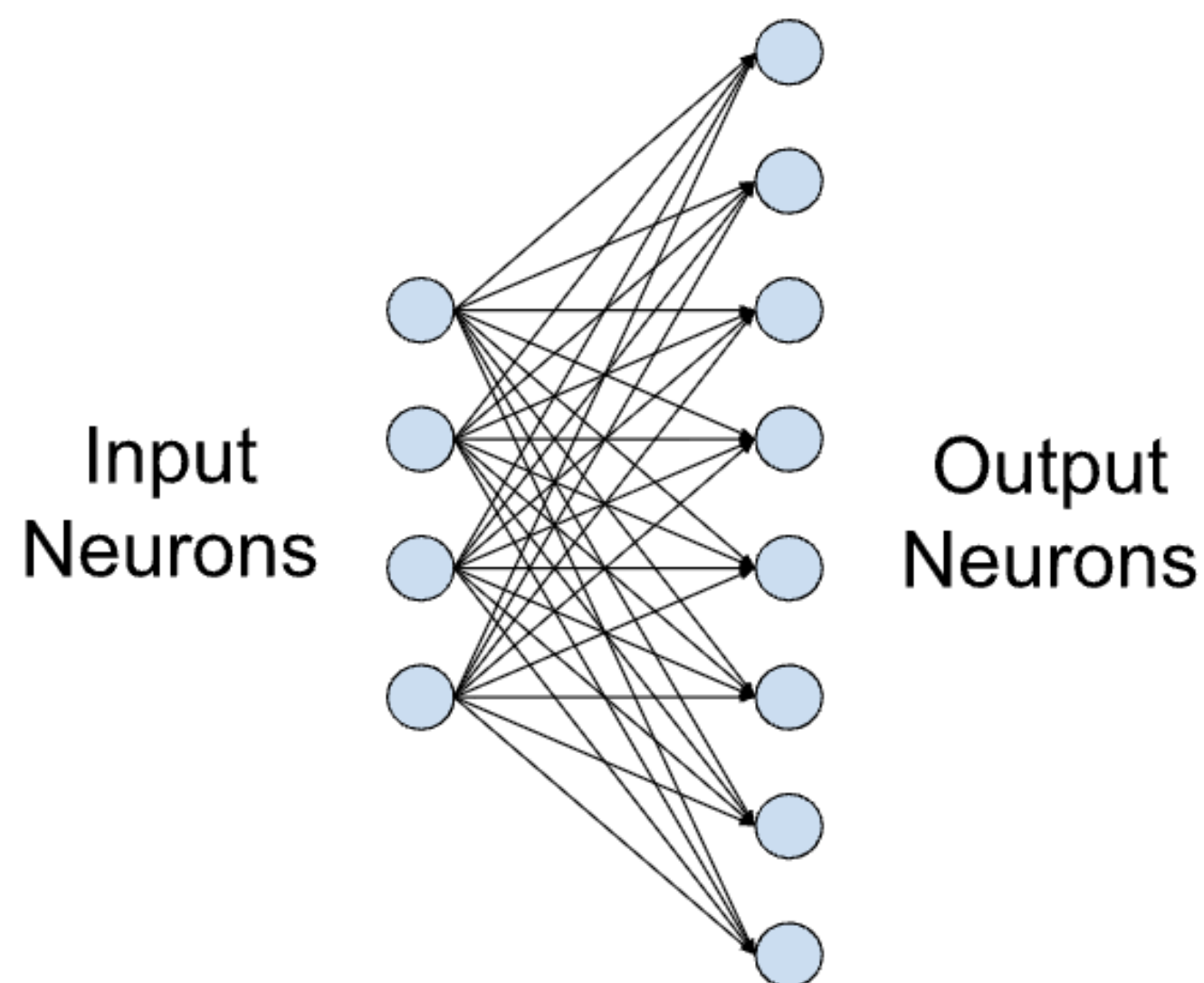
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- **MaxPool2d: downsampling**



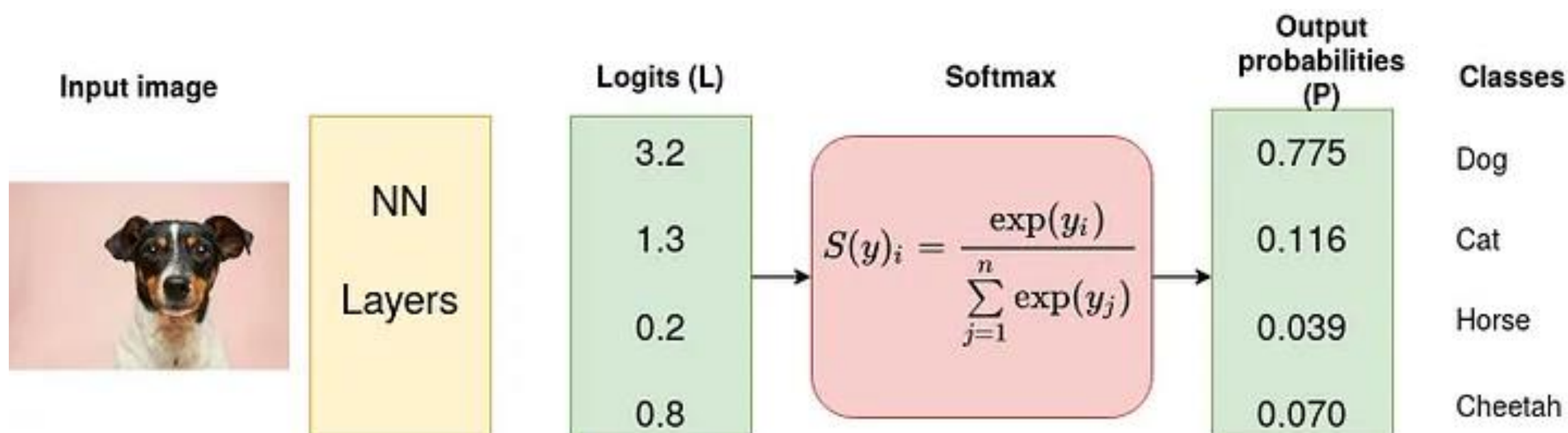
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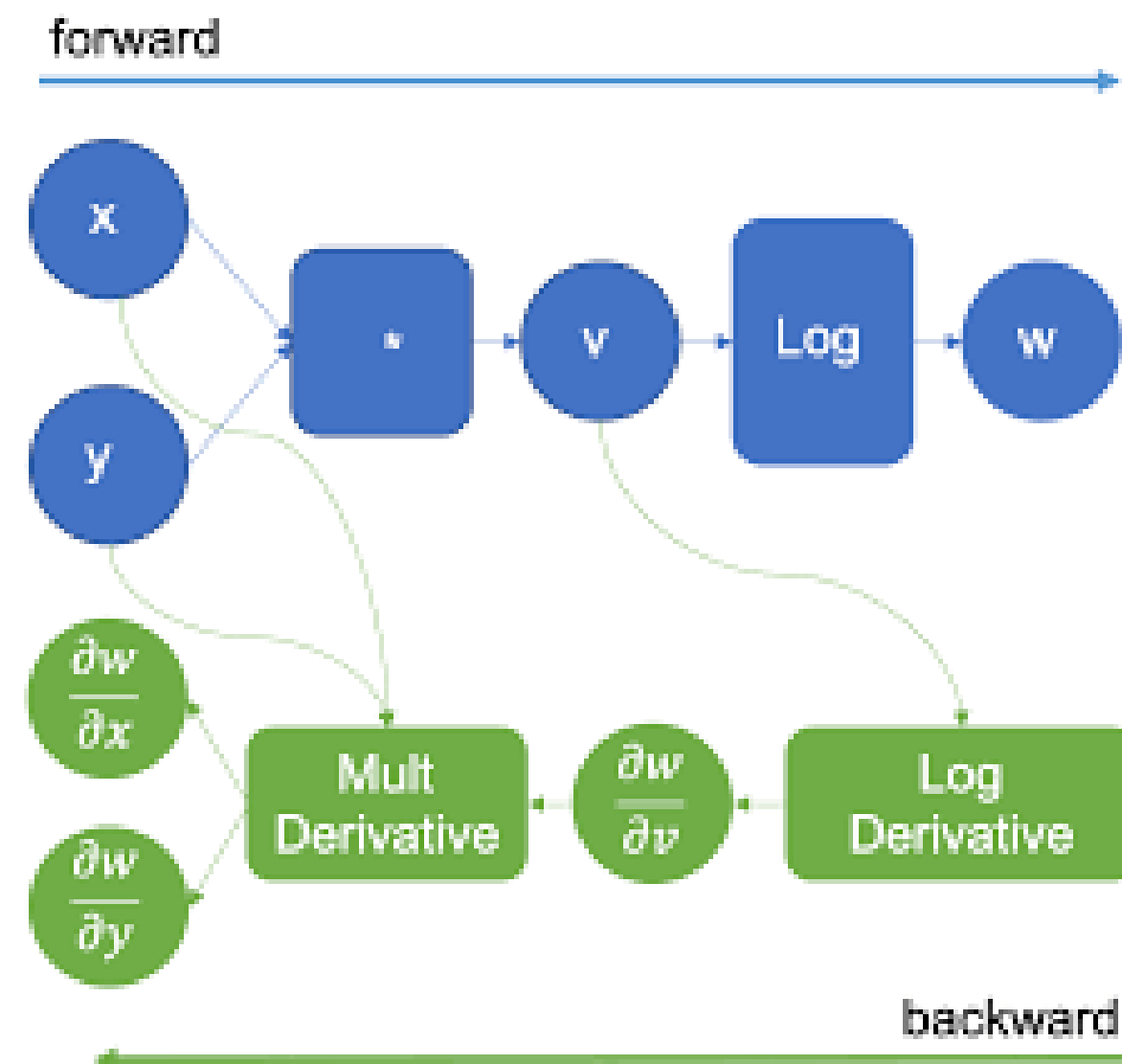
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# Autograd and Computational Graph

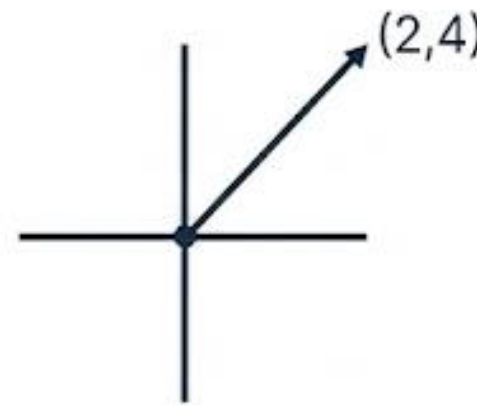
- PyTorch dynamically builds a computation graph as operations run
- Each operator records gradient computation rules
- `loss.backward()` traverses the graph automatically
- Gradients stored in `tensor.grad`



# Tensors: The Heart of PyTorch

- Similar to NumPy arrays but GPU accelerated
- Support automatic differentiation for deep learning
- Example shapes: Image [3,32,32], Batch [64,3,32,32]
- Common ops: `torch.add`, `torch.mul`, `torch.matmul`, `torch.mean`, `torch.cat`

**Tensors** are the **core data structure** in PyTorch, optimized with **GPU acceleration** for faster computations.



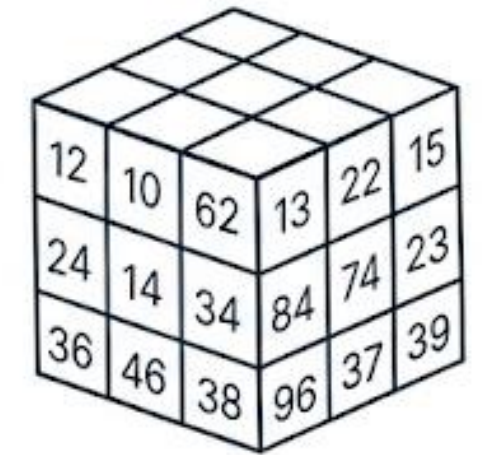
**Vectors**

Simple list of Numbers

|    |    |    |
|----|----|----|
| 12 | 58 | 9  |
| 24 | 61 | 2  |
| 36 | 11 | 88 |

**Matrices**

Grid of Numbers



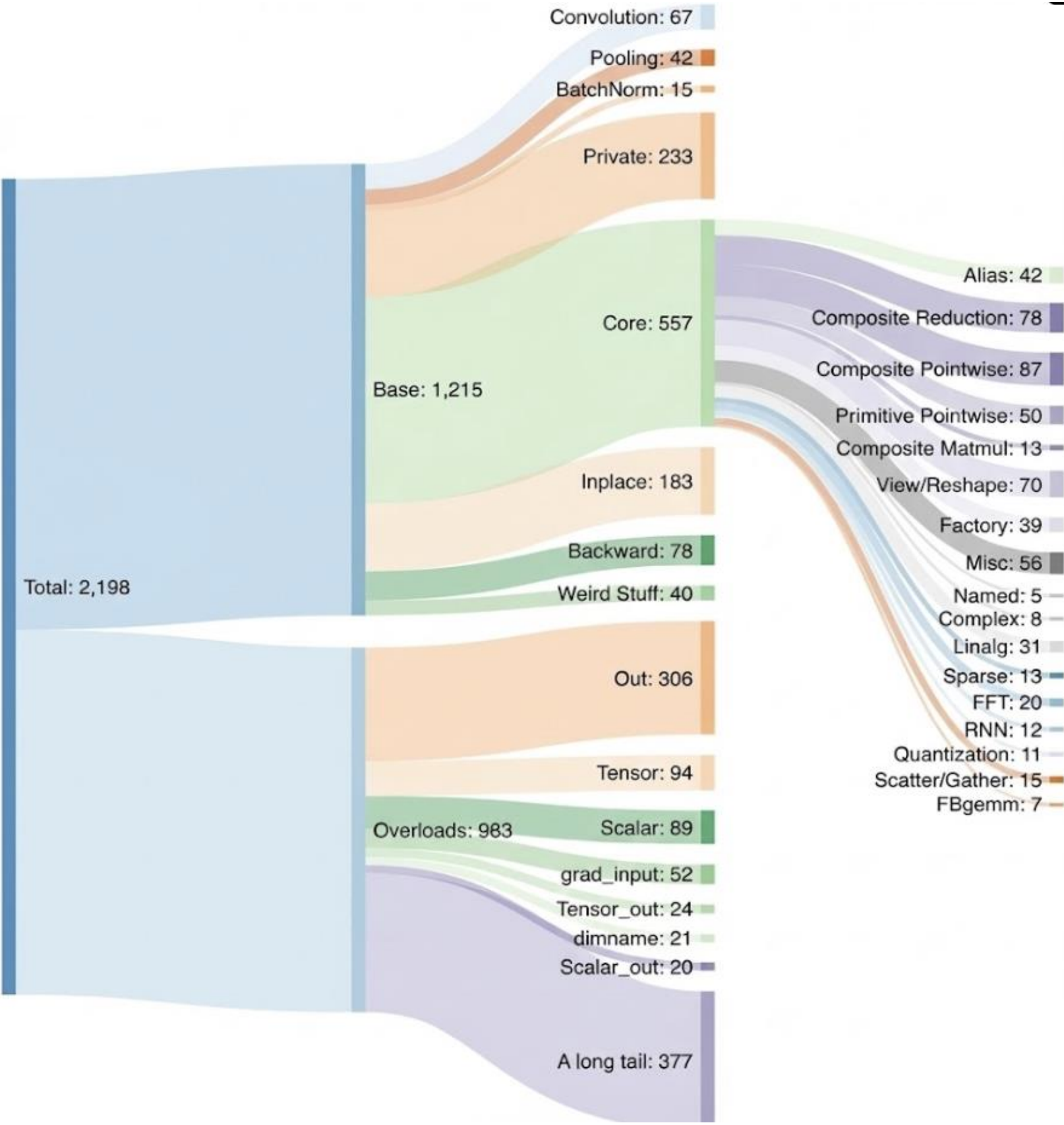
**Tensors**

Multi-dimensional Data

# Tensors: The Heart of PyTorch

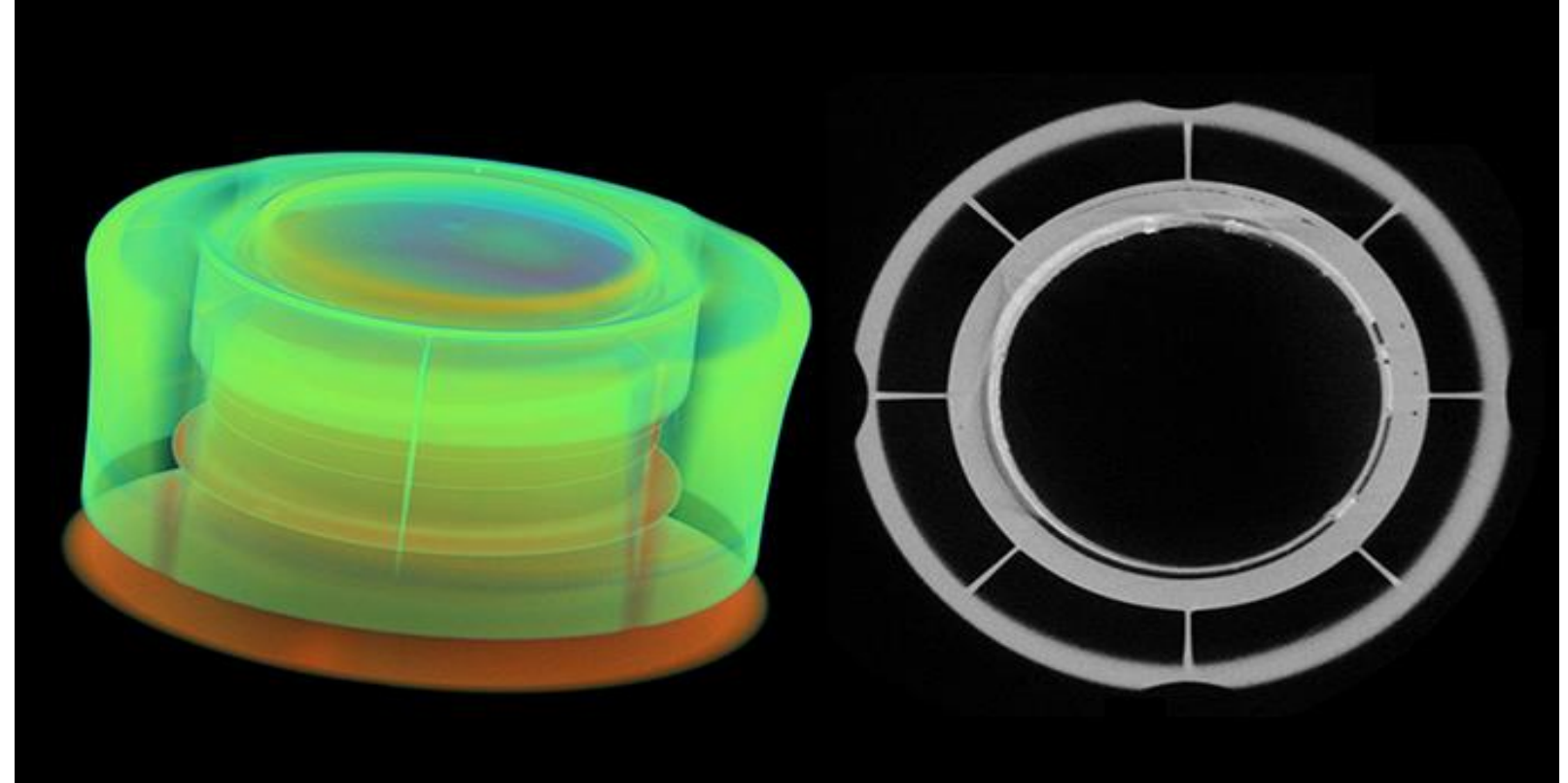
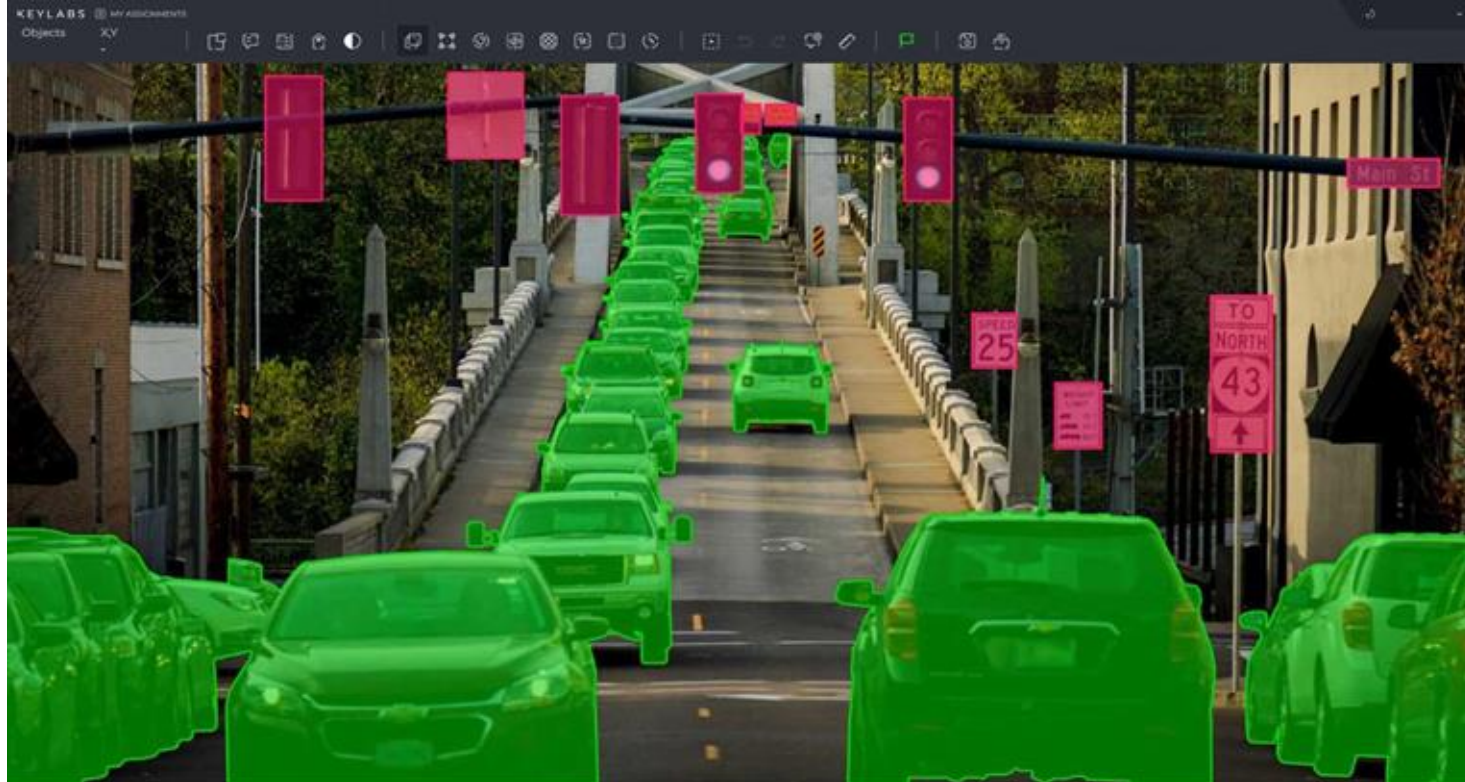
PyTorch Data Types Reference Table

| Data type                | CPU tensor         | GPU tensor              |
|--------------------------|--------------------|-------------------------|
| 32-bit floating point    | torch.FloatTensor  | torch.cuda.FloatTensor  |
| 64-bit floating point    | torch.DoubleTensor | torch.cuda.DoubleTensor |
| 16-bit floating point    | torch.HalfTensor   | torch.cuda.HalfTensor   |
| 8-bit integer (unsigned) | torch.ByteTensor   | torch.cuda.ByteTensor   |
| 8-bit integer (signed)   | torch.CharTensor   | torch.cuda.CharTensor   |
| 16-bit integer (signed)  | torch.ShortTensor  | torch.cuda.ShortTensor  |
| 32-bit integer (signed)  | torch.IntTensor    | torch.cuda.IntTensor    |
| 64-bit integer (signed)  | torch.LongTensor   | torch.cuda.LongTensor   |



# Real-World Applications

- Object recognition for autonomous systems.
- Medical diagnostics and defect detection.
- Wildlife monitoring and smart city vision.
- Foundation for detection and segmentation tasks.





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