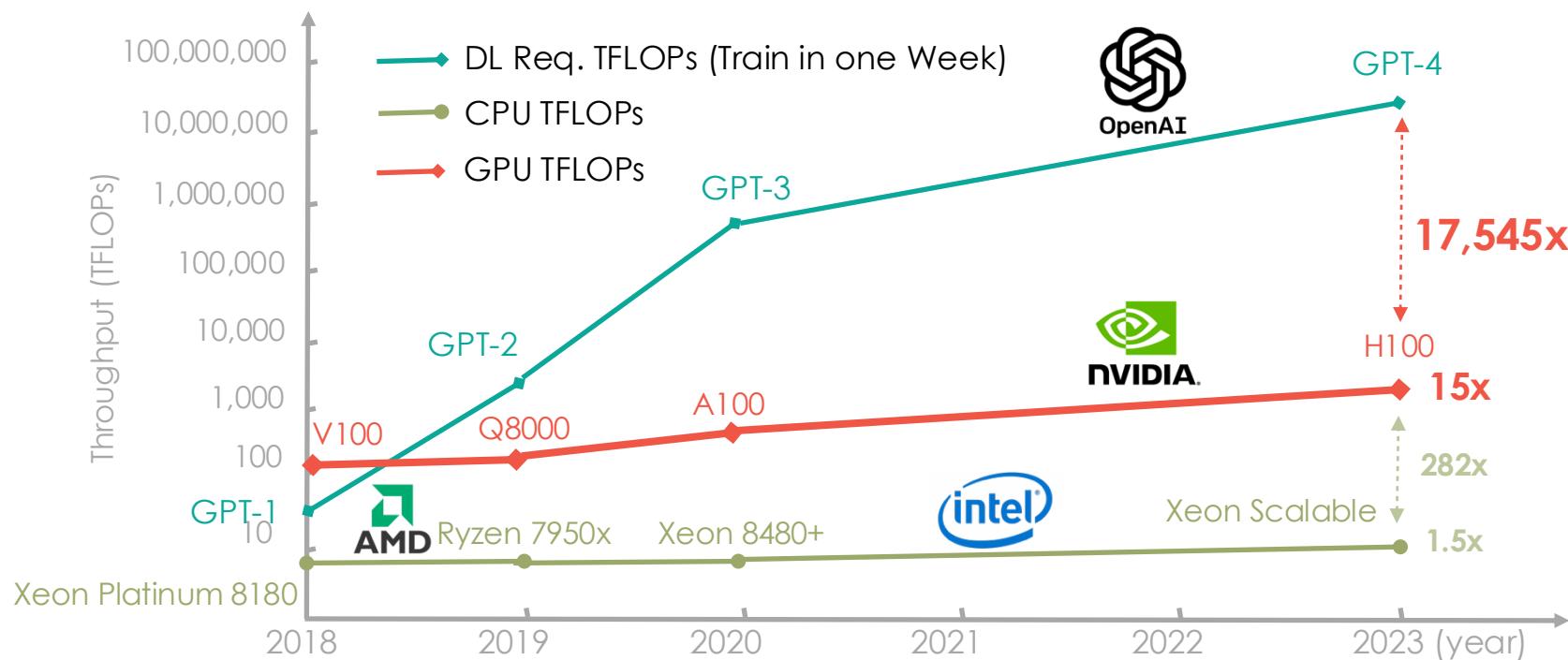


# Systematic Approaches for Efficient and Scalable Deep Learning

**Yuke Wang**  
Computer Science  
Rice University

# The Trend of DL Algorithm and Hardware

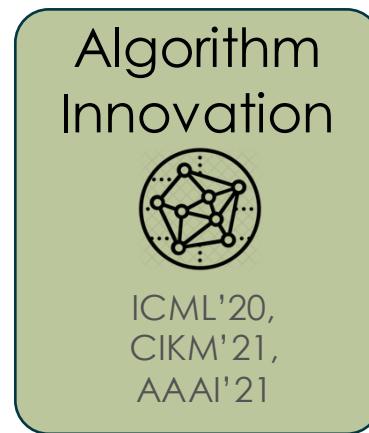
- ❖ Recap of DL algorithms and hardware performance scaling.



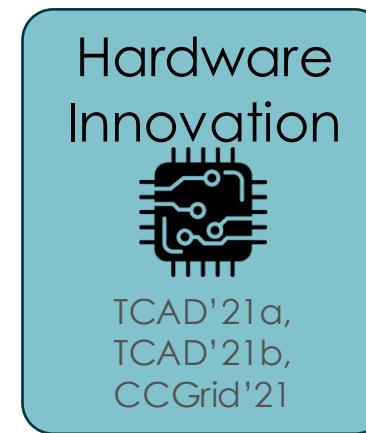
Huge Potential with GPUs! But it still has a **Large Gap!**

# Deep Learning Drives Computing Innovations

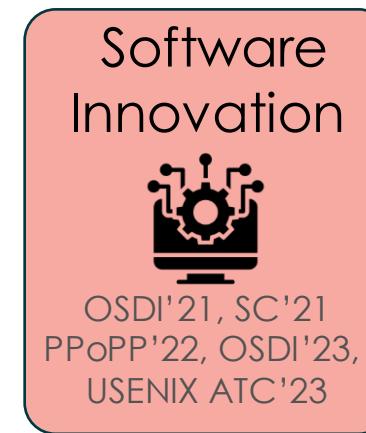
- ❖ Overview of my prior Ph.D. Research.



Model Design,  
Model Pruning  
(2018-19)

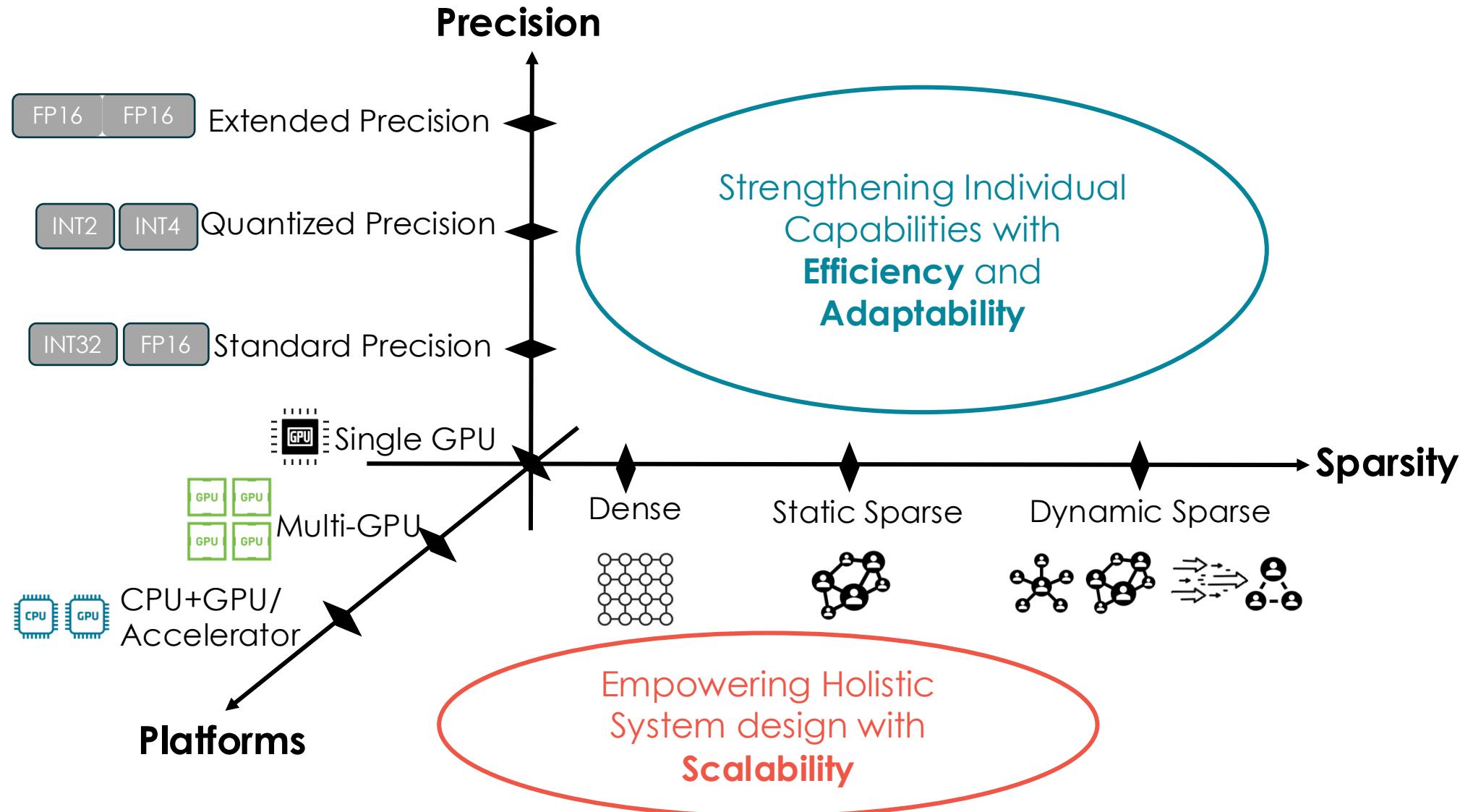


Hardware  
Accelerators  
(2020-21)

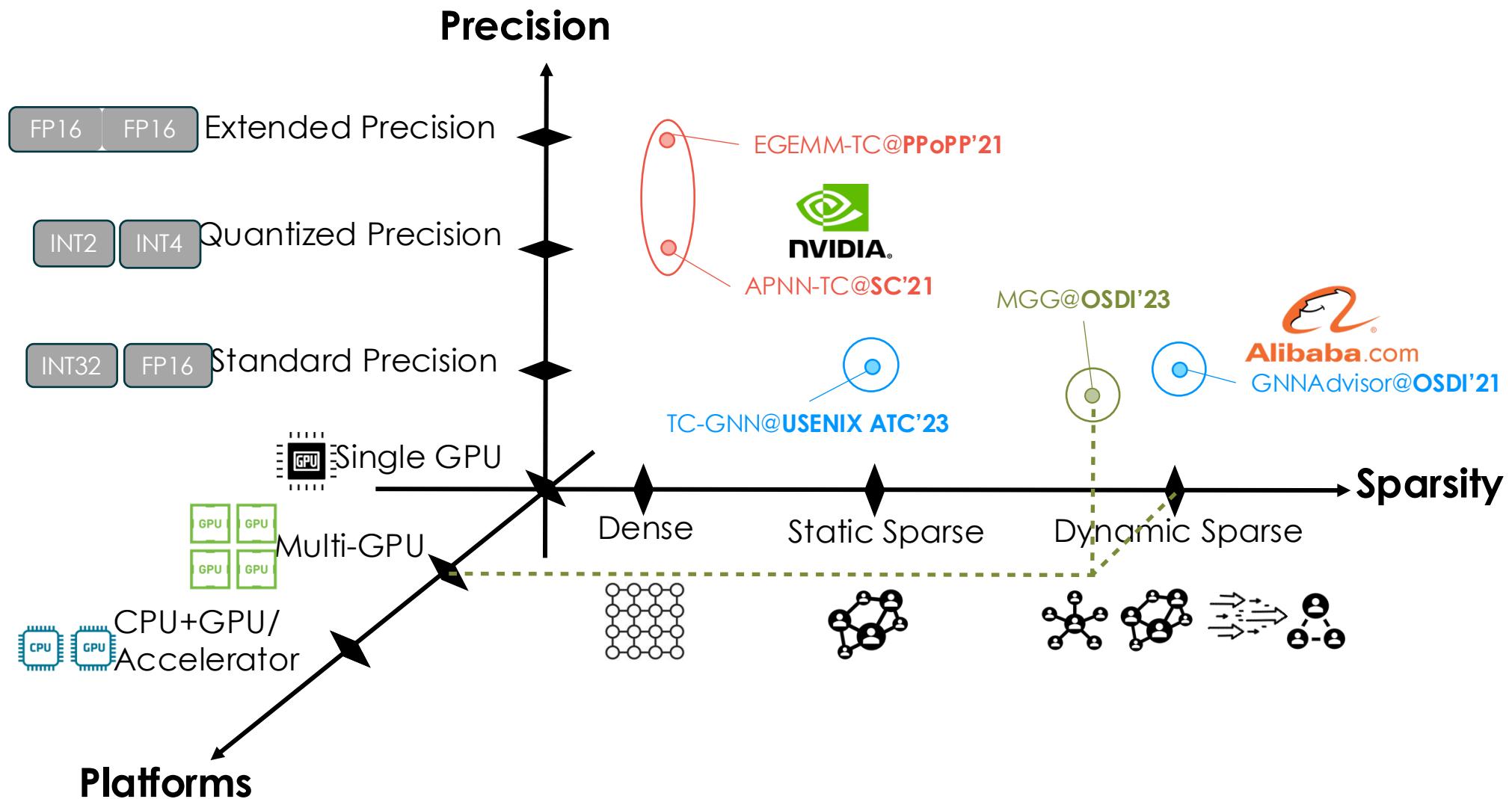


Runtime Systems,  
Compiler  
(2021-now)

# My Prior Ph.D. Research Recap



# My Prior PhD Research Recap



# Diverse Precision Demands for DL Applications

- ❖ **Low-precision** quantized deep-learning applications.

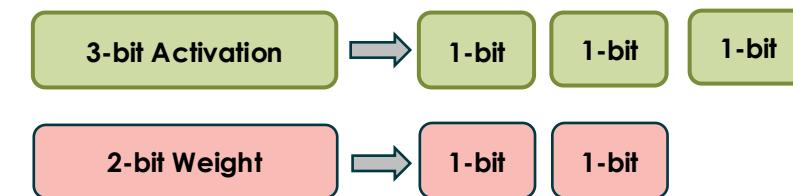
Quantized Deep Learning	Precision Requirements
QNNs [JMLR'18]	1-bit <b>Weight</b> , 2-bit <b>Activation</b> for Vision Model, 3-bit <b>Weight</b> , 4-bit <b>Activation</b> for Language Model.
SGQuant [ICTAI'20]	Graph Attention Model: <b>2-bit</b> Neighbor <b>Attention</b> , <b>4-bit</b> Neighbor <b>Aggregation</b> .
LLM.int8() [NeurIPS'22]	<b>8-bit</b> Quantization for Transformers.
...	...



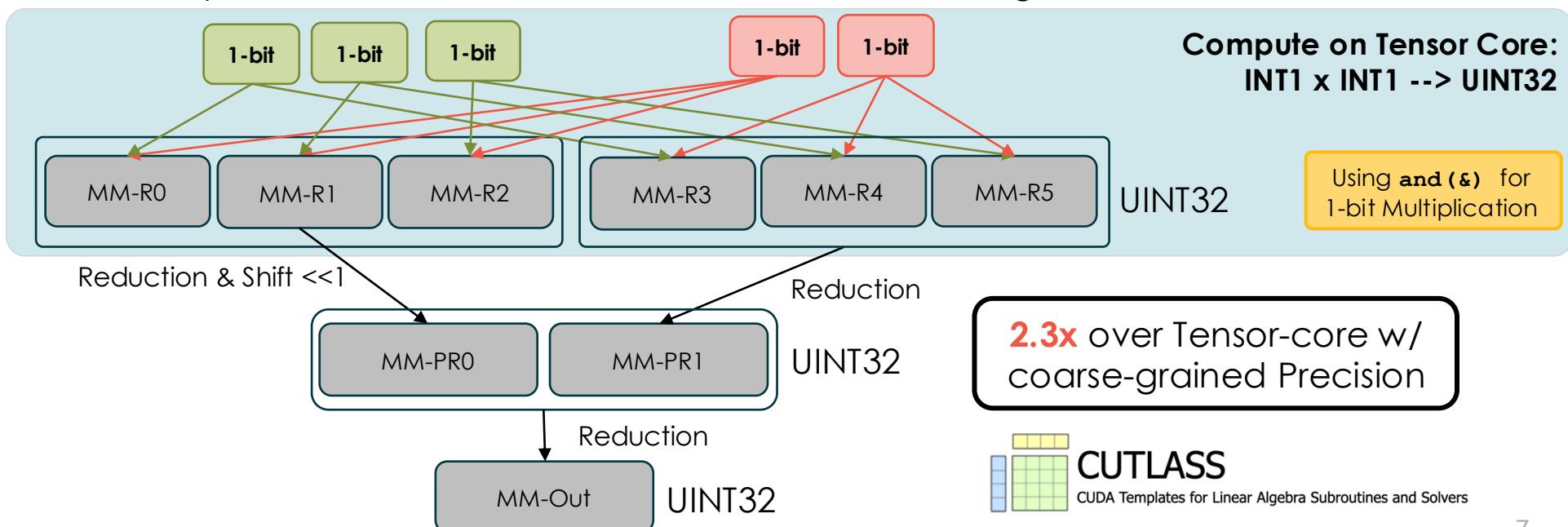
# Bit Composition for Quantized Deep Learning [SC'21]

- ❖ Insight: **Quantized deep learning** can be **composed** with the **binary (1-bit) precision**.

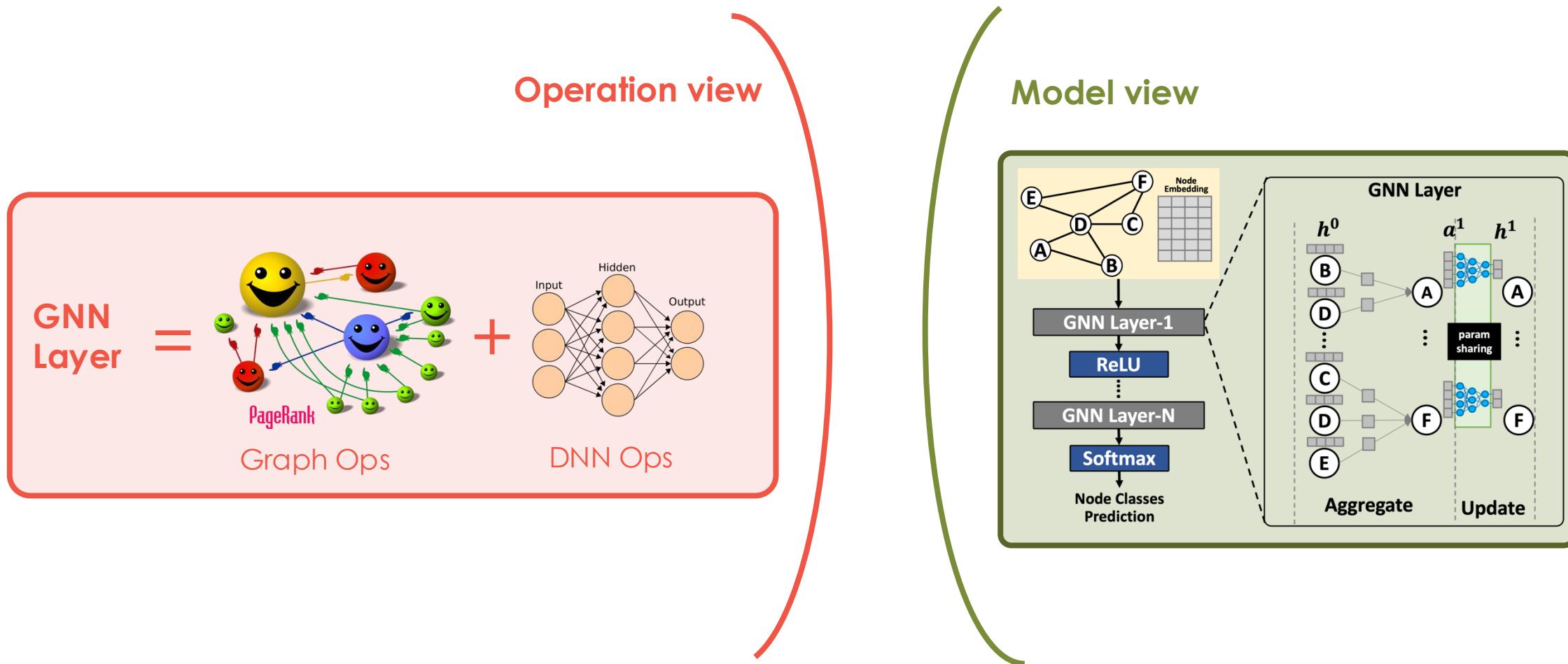
Example of **2-bit** and **3-bit** Precision in Quantized DNN Computing.



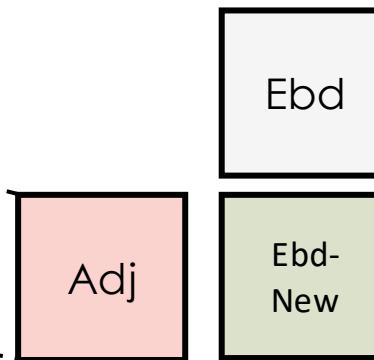
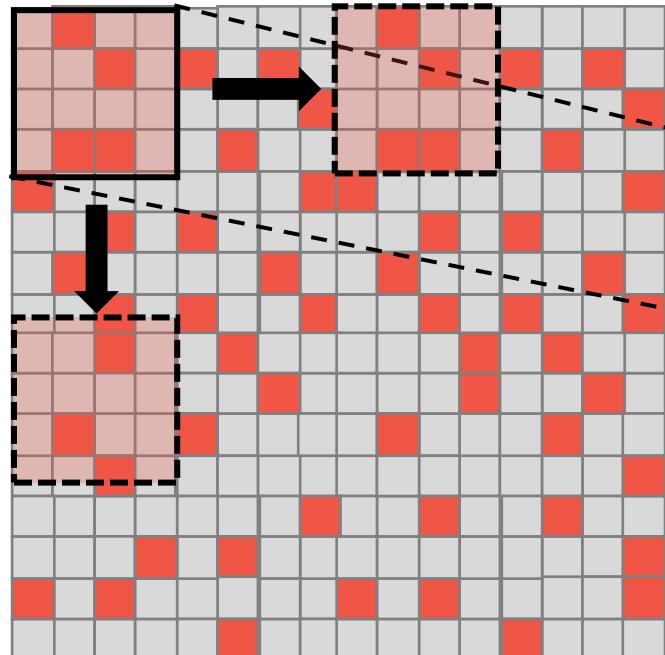
Multiplication between 3-bit Activation and 2-bit Weight



# A Typical Paradigm of Graph Deep Learning



# Challenge of Mapping Sparse Computing to Dense Units



>> A100/H100  
(80GB)

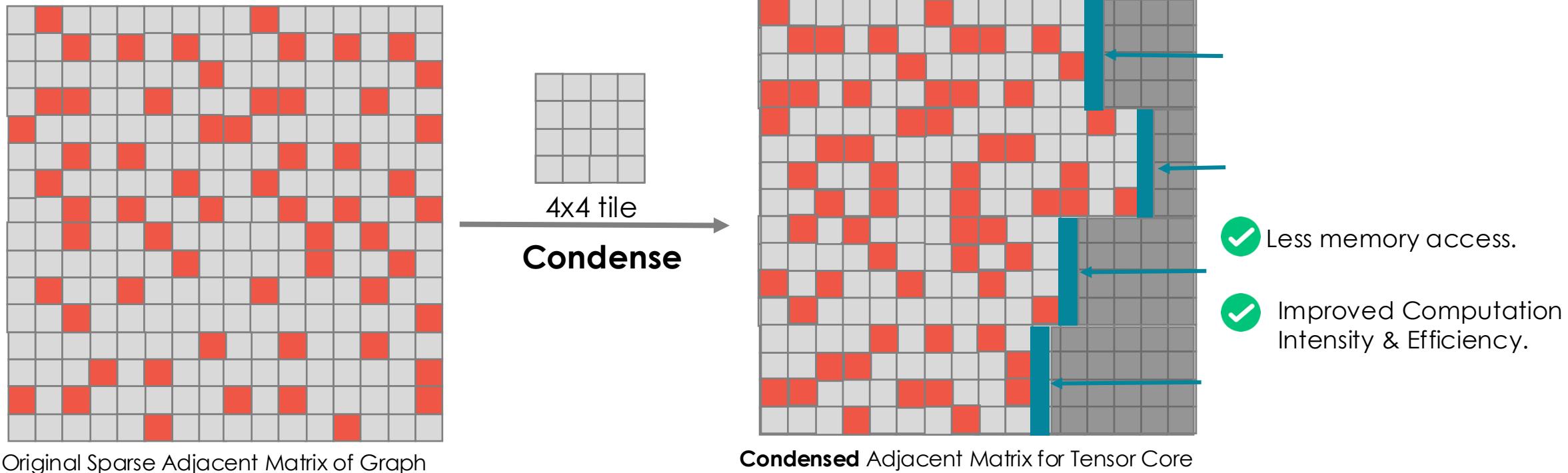
Dataset	# Nodes	# Edges	Memory	Eff.Comp
OVCR-8H	1,890,931	3,946,402	14302.48 GB	0.36%
Yeast	1,714,644	3,636,546	11760.02 GB	0.32%
DD	334,925	1,686,092	448.70 GB	0.03%

Largely **Wasted** Computation  
and Memory Access

Direct mapping: **high memory** consumption  
and **low computing** efficiency.

# TC-GNN: Order-Invariant Transformation [ATC'23]

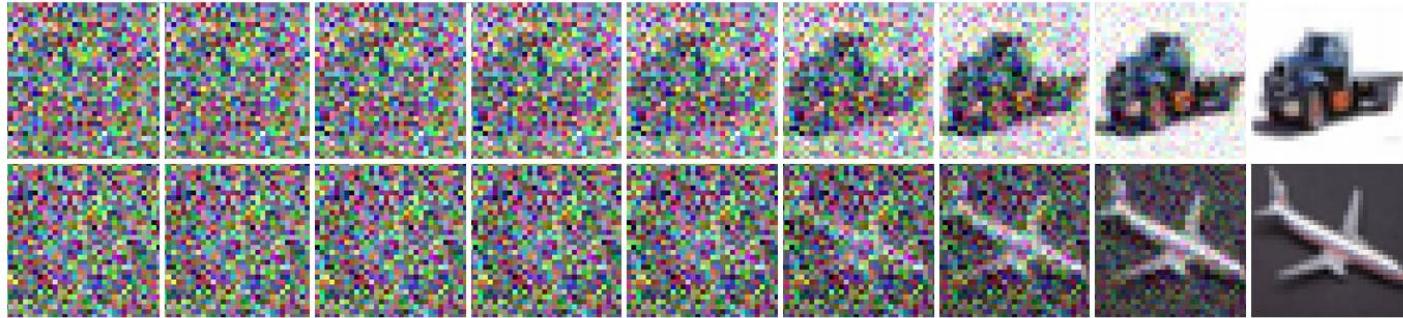
- Irregularly-scattered elements can be **condensed** to benefit high-performance dense GPU units.



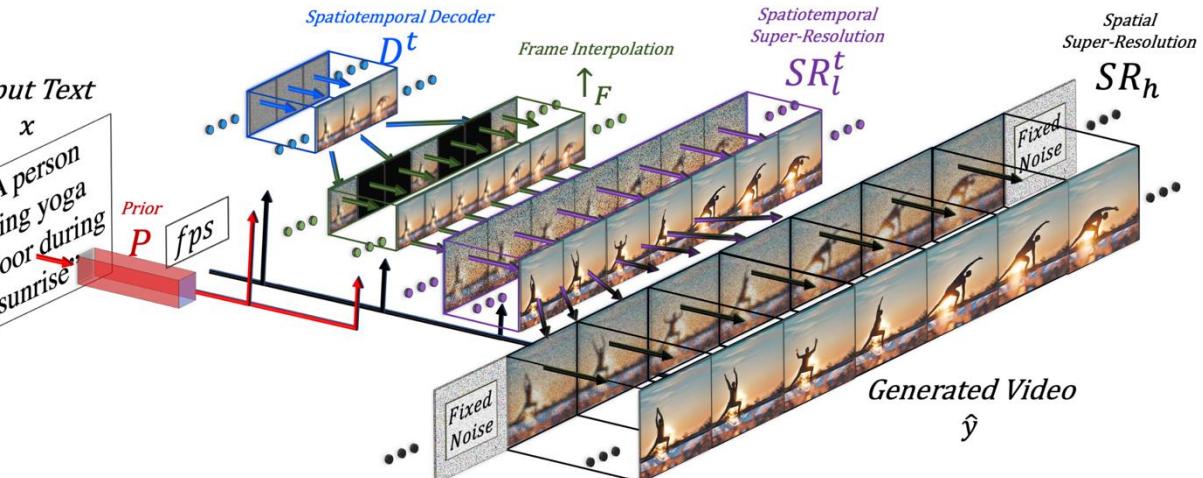
**1.50x ~ 6.70x** over DGL operators (cuSPARSE).

Incorporated by SparseTIR in **TVM** Project.

# In The Era of Generative AI

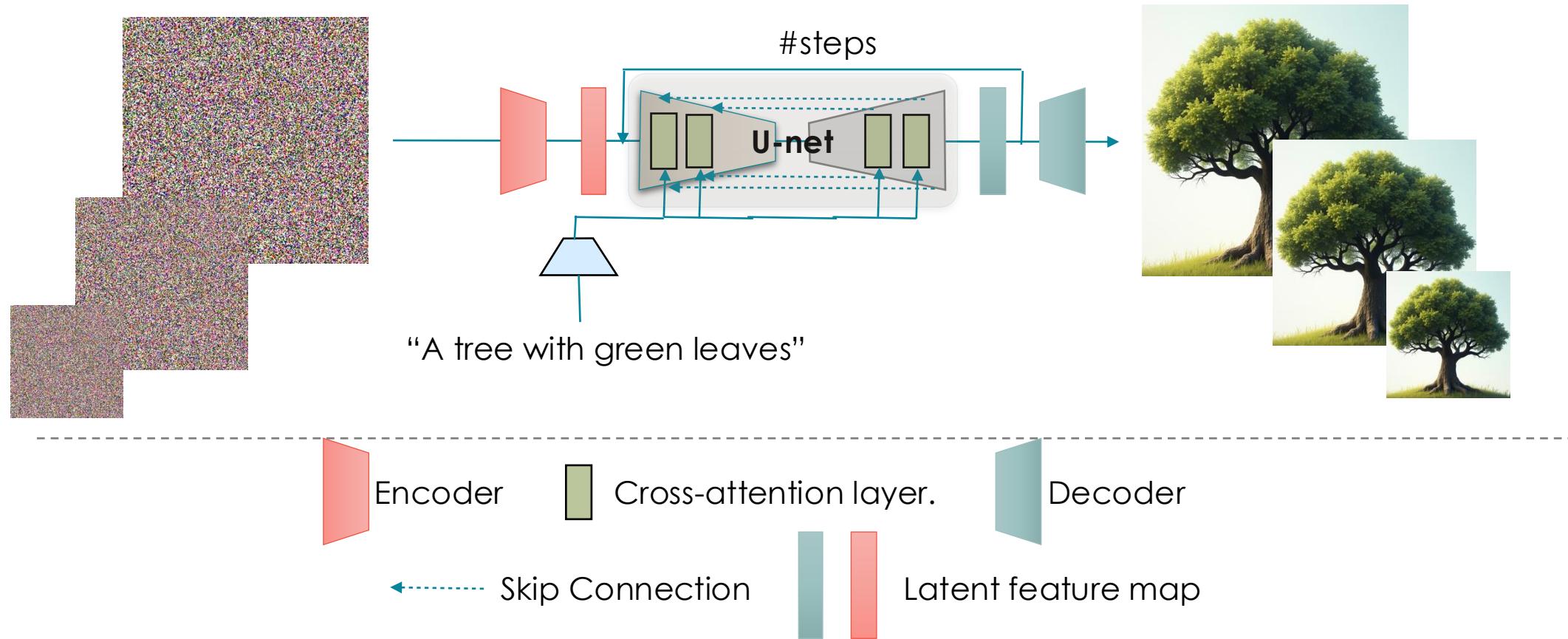


denoise ↑ denoise ↑



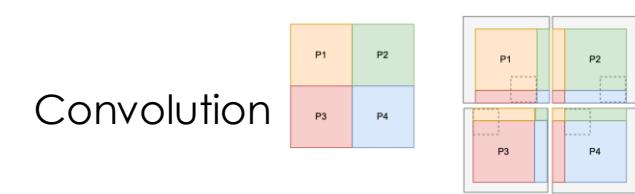
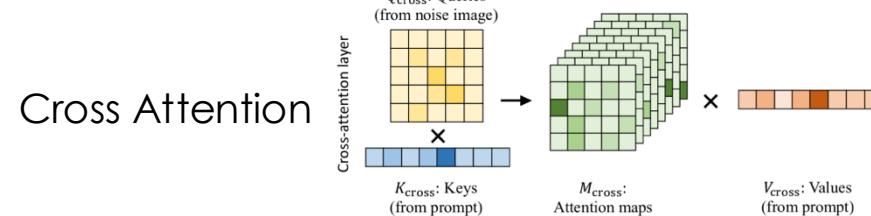
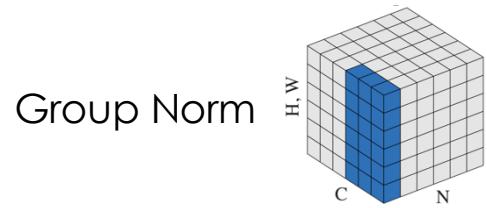
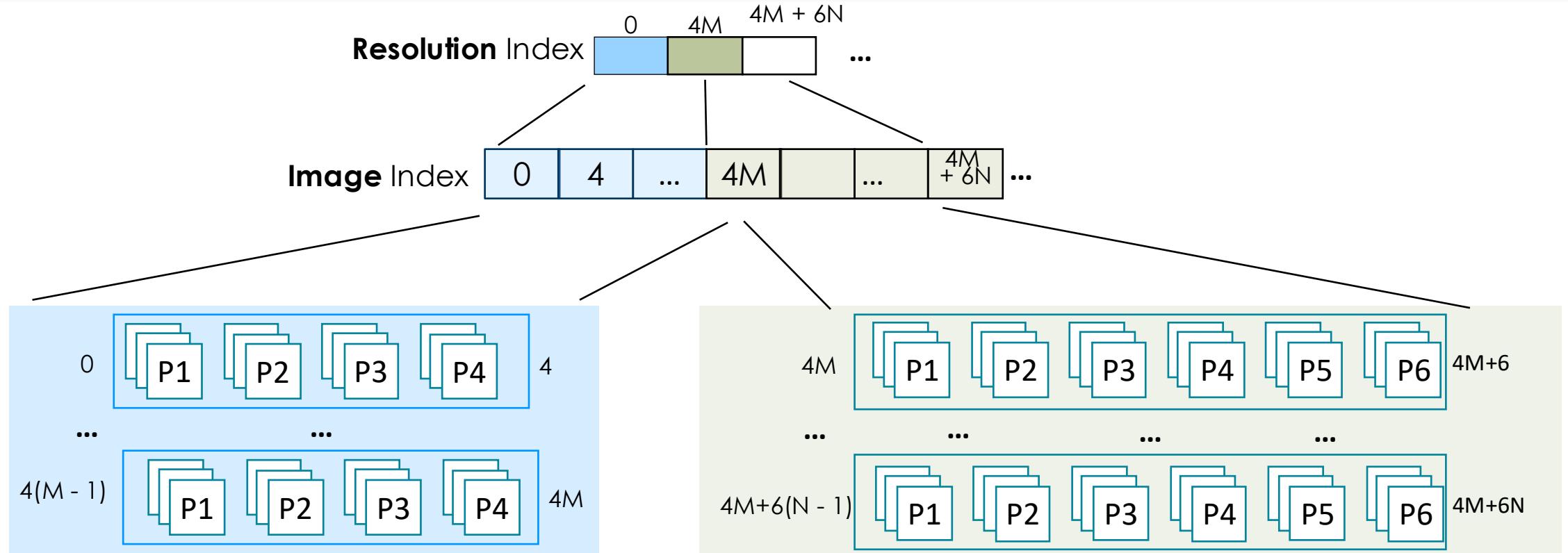
# Patch-based Diffusion Serving [PPoPP'26]

- Architecture of **Image Diffusion** Model.



Note that Conv are omitted in Unit for simplicity.

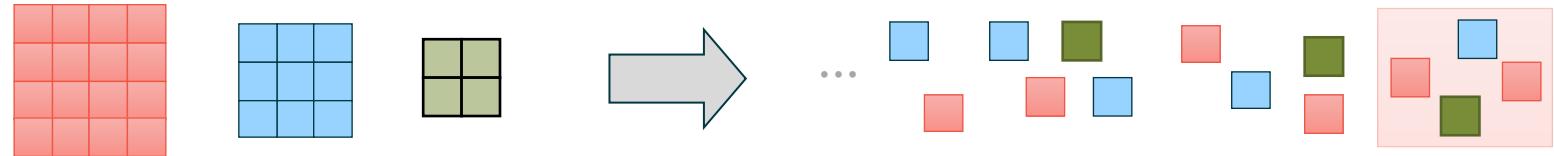
# Hierarchical Tile Storage and Indexing



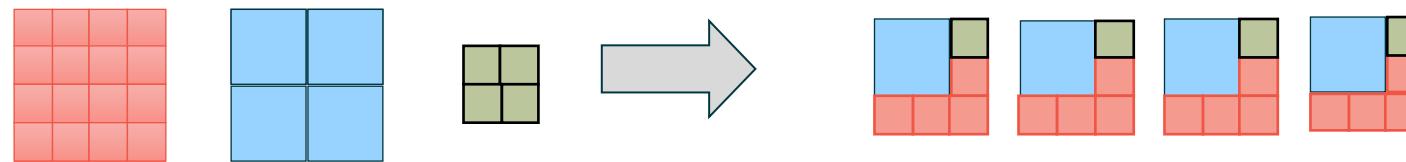
Note that the common factor of  $C \cdot H \cdot W$  is omitted for simplicity.

# Tile-based Workload Scheduling

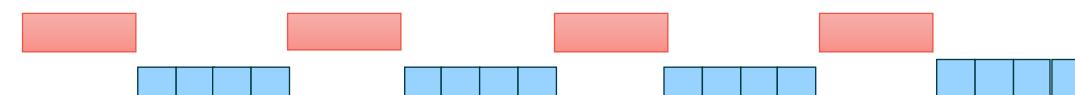
Unify the processing of different resolutions



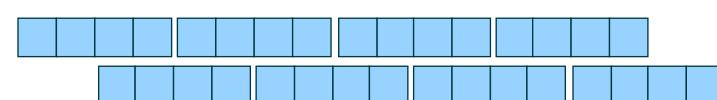
Control granularity for mixed workload composition



Unlock more fine-grained pipelining (FCFS)



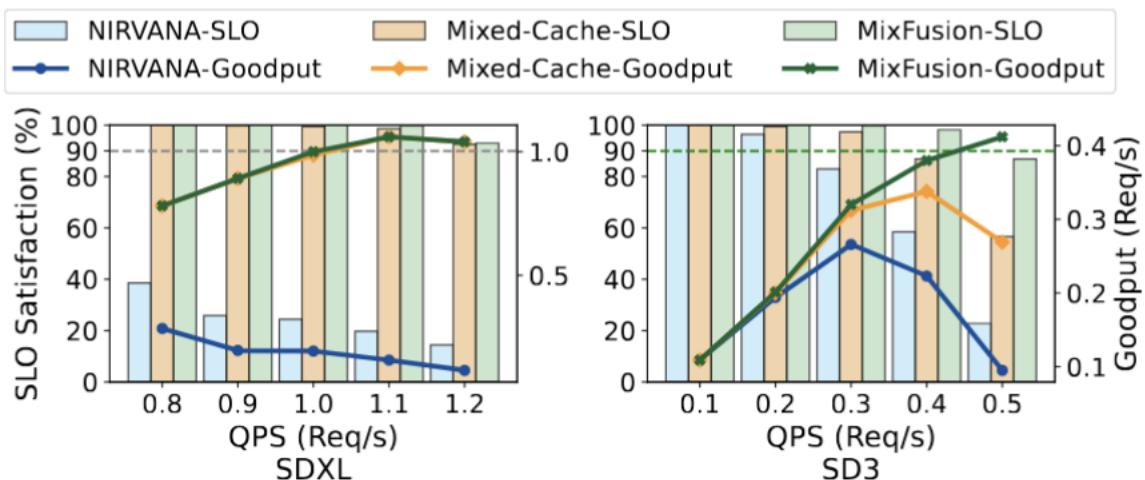
a. Resolution-mismatch for largely sequential processing.



b. Decomposed Resolution for batched processing.

# Evaluation

- End-to-End SLO satisfaction Ratio



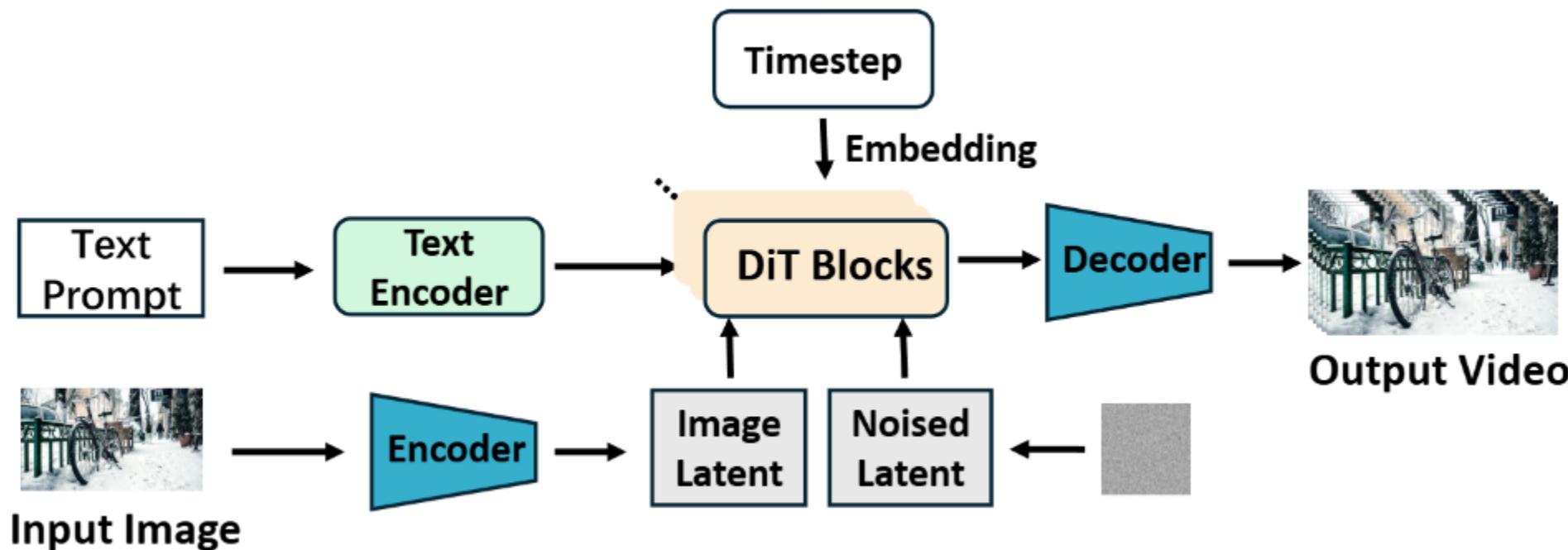
- Quality Score Comparison

Model	Method	SDXL		SD3	
		COCO	diffusiondb	COCO	diffusiondb
CLIP ( $\uparrow$ )	Original	14.92	16.24	14.79	16.65
	MIXFUSION	<b>15.43</b>	<b>16.62</b>	<b>15.13</b>	<b>17.06</b>
FID ( $\downarrow$ )	Original	31.92	35.56	28.94	<b>32.38</b>
	MIXFUSION	<b>28.85</b>	<b>33.42</b>	<b>26.56</b>	38.01

**5.33× higher goodput** when achieving **90 % SLO**  
while over SOTA NIRVANA [1]

# Ultra-Resolution Video Generation

- Architecture of Diffusion Transformer Model.



# Observation of Ultra-high-resolution Video Generation

- Maximum supported resolution and running time

Model	Max Resolution	Frames	VRAM	Latency
CogVideoX1.5 5B [15]	$1360 \times 768$	80	40GB	400s
HunyuanVideo 13B [20]	$1280 \times 720$	128	70GB	1,800s

$$T_{4K} \approx 1800s \times \left( \frac{3840 \times 2160}{1280 \times 720} \right)^2 / 3600 \approx 40 \text{ h},$$

How to training-free and efficiently to generate ultra-high-resolution video?

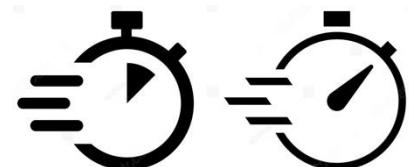
## Why only supports 720p

Not enough high-resolution training datasets. (Billions)

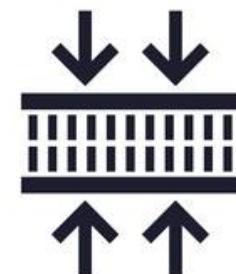


Data Being Generated

**Generation inefficiency**  
5-second 4K video directly could take a day and intensive memory cost.

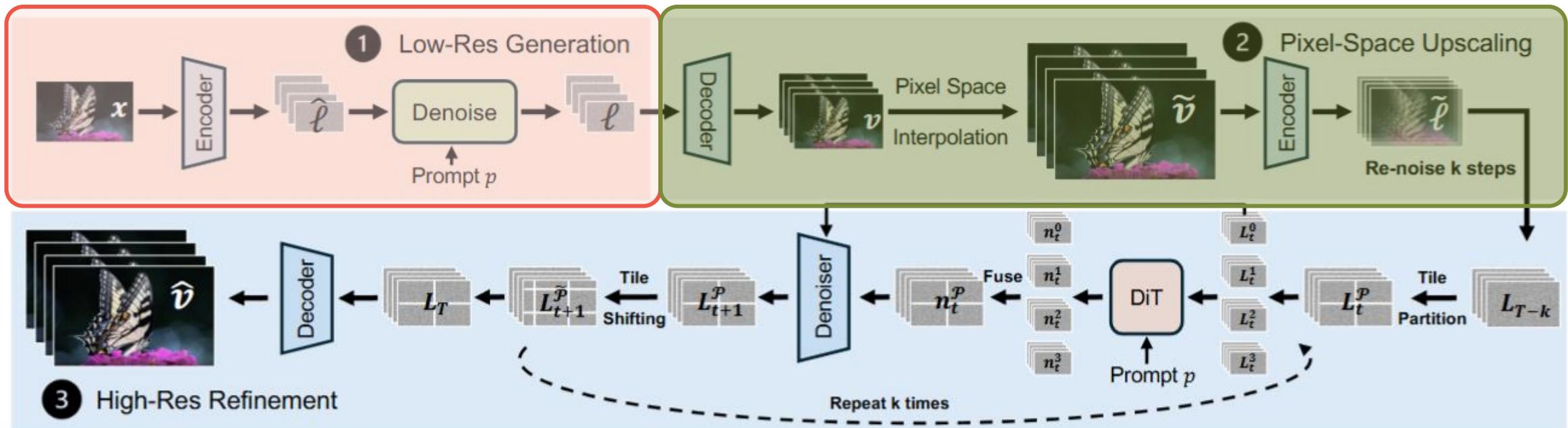


**Current super-resolution video generation?**  
Only fixed scale factor, not training-free



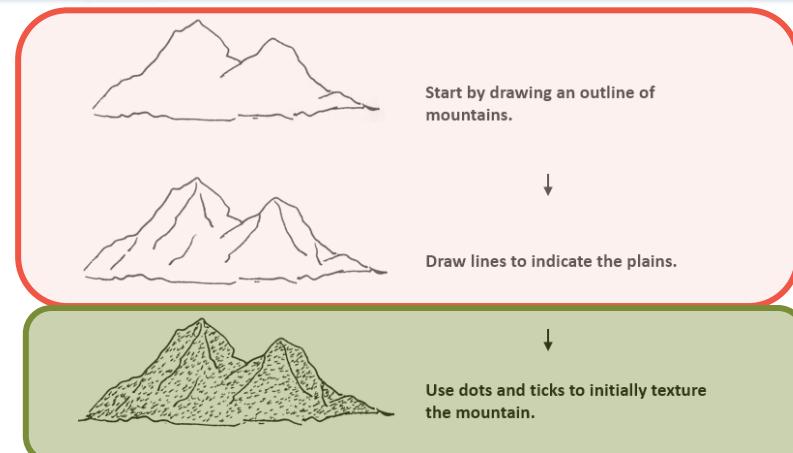
# Opportunity: Sketching and Tiling

- Training-free Two-stage Generation



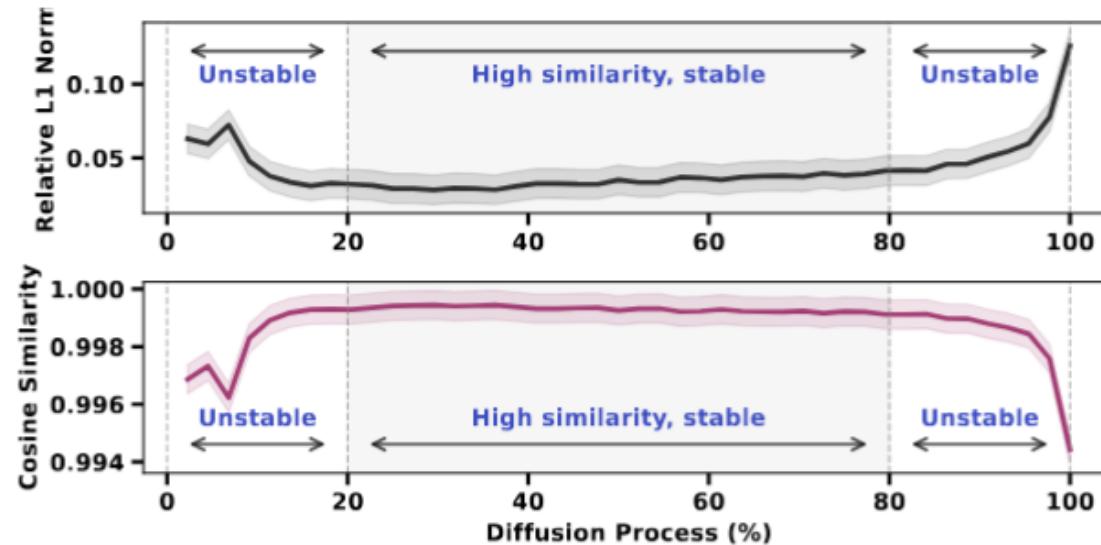
First stage: **Global Semantic Guidance**

Second stage: **Local Details Refinement**



# System Support: Fine-grained Cache

- Observation: High similarity of predicted noise across timestep



$$L1_{rel}(\mathbf{O}, t) = \frac{\|\mathbf{O}_t - \mathbf{O}_{t+1}\|_1}{\|\mathbf{O}_{t+1}\|_1}, \text{CosSim}(\mathbf{O}, t) = \frac{\langle \mathbf{O}_t, \mathbf{O}_{t+1} \rangle}{\|\mathbf{O}_t\|_2 \|\mathbf{O}_{t+1}\|_2}$$

How to Utilize this Similarity?

# System Support: Fine-grained Caching Strategy

- Fine-grained Region-aware Cache

Introduce cache residual  $\delta_t \triangleq O_t - I_t$

Approximate  $O_t \approx I_t + \delta_t$ .

Error Accumulation  $E_{c \rightarrow t} = \sum_{k=c+1}^t \|O_k - O_{k-1}\|$ .

Involve transformation rate  $k_t = \frac{\|\mathbf{O}_t - \mathbf{O}_{t-1}\|}{\|\mathbf{I}_t - \mathbf{I}_{t-1}\|}$ .

$$E_{c \rightarrow t} \approx \sum_{k=c+1}^t k_c \|I_k - I_{k-1}\| = k_c \sum_{k=c+1}^t \|I_k - I_{k-1}\| = k_c L_{c \rightarrow t},$$

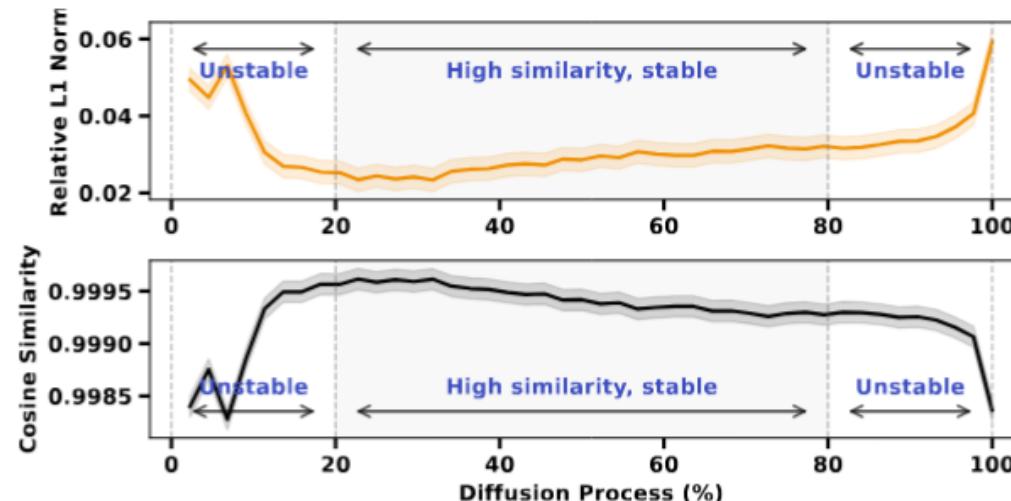
Cache Decision

if $k_c L_{c \rightarrow t} < \tau$	$\Rightarrow$ reuse cache at step $t$ ,
else $k_c L_{c \rightarrow t} \geq \tau$	$\Rightarrow$ recompute $O_t$ and set $c \leftarrow t$ .

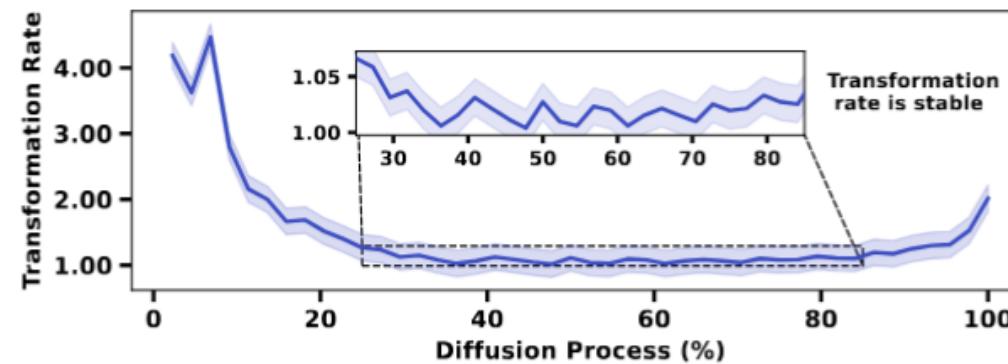
1) **Predict** next diffusion step **outcome** based on current outcome.

2) **Accumulate** the prediction **errors** to determine caching.

High similarity of Cache Residual

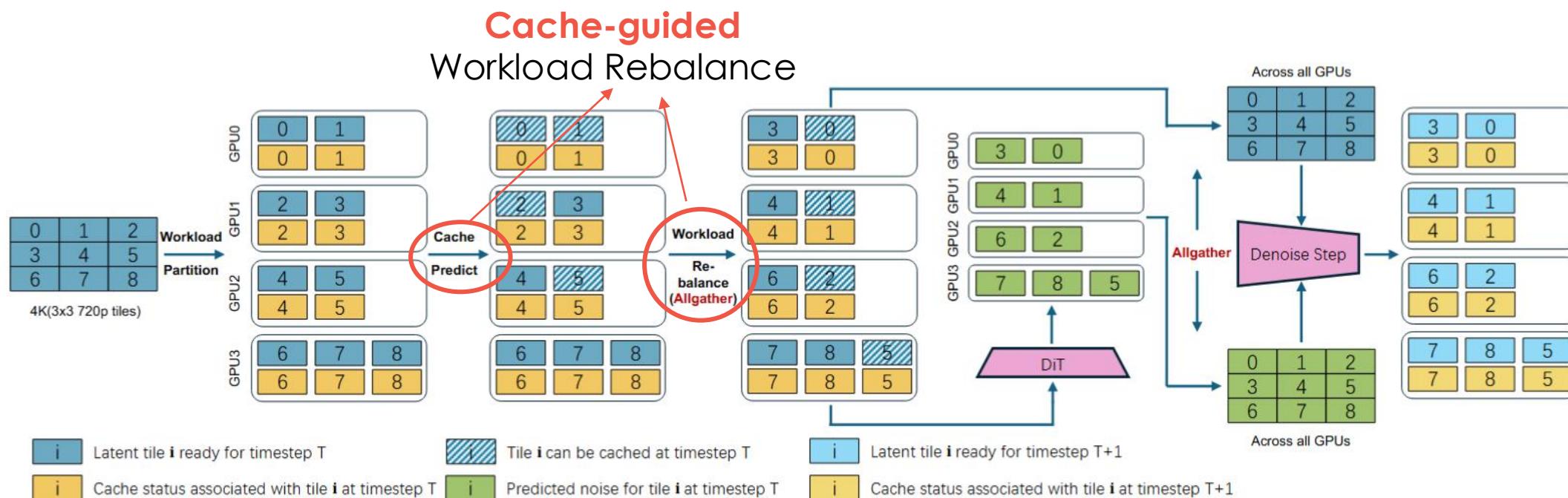


Transformation Rate K is Stable



# System Support: Intelligent Cost-efficient parallelism

Workload imbalance: e.g., 9 tiles on 4 GPUs



QKV in different tile are **independent**,  
Minimum communication.

1) Reuse the computed tiles in **nearby GPUs**.

2) Reuse the computed tiles in from **prior iteration**.

# Evaluation: Video Quality

Table 2: Quality results of SUPERGEN on VBench benchmark. V1–V5 denote the five evaluation metrics: **V1**: Subject Consistency, **V2**: Background Consistency, **V3**: Motion Smoothness, **V4**: Aesthetic Quality, and **V5**: Imaging Quality.

Model	Setting	V1(%)	V2(%)	V3(%)	V4(%)	V5(%)	Avg.
Cogvideo	720p	96.29	96.23	98.41	61.88	70.20	<b>84.60</b>
	2K w/o Cache	95.66	96.06	97.22	63.86	70.38	<b>84.64</b>
	2K w/ Cache	95.45	95.91	97.21	62.75	69.75	<b>84.21</b>
	4K w/o Cache	92.94	94.11	98.10	57.92	67.38	<b>82.09</b>
	4K w/ Cache	93.22	94.32	98.04	57.95	67.56	<b>82.22</b>
Hunyuanyvideo	720p	98.55	97.86	99.53	64.54	70.83	<b>86.26</b>
	2K w/o Cache	98.02	97.31	99.42	66.47	69.62	<b>86.17</b>
	2K w/ Cache	98.30	97.48	99.44	66.16	70.26	<b>86.33</b>
	4K w/o Cache	97.76	97.24	99.43	63.07	69.68	<b>85.44</b>
	4K w/ Cache	98.12	97.58	99.51	62.57	70.31	<b>85.62</b>

Both 2K and 4K can achieve **high quality**.

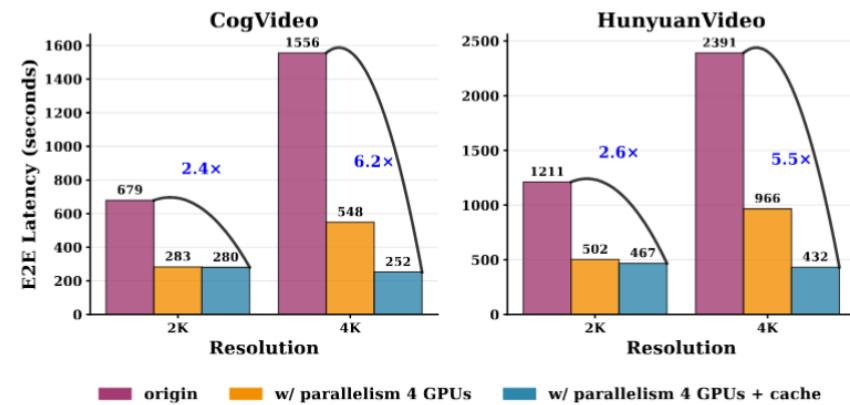
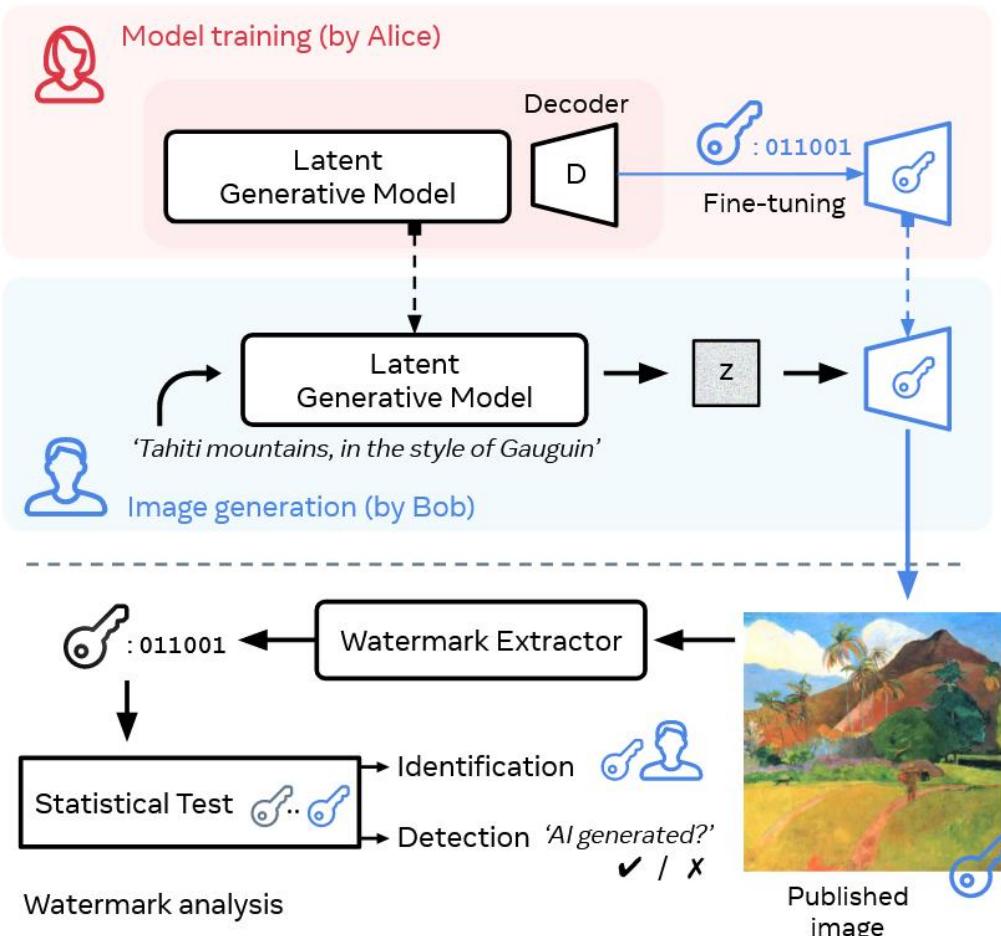


Figure 12: End-to-end latency. Origin setting is evaluated with 1 GPU without cache. The other two settings with parallelism are measured with workload rebalance.

End-to-end can achieve up to **6.2x** speedup.

# Efficient and Adaptive Watermark Detection

- Overview of diffusion image watermarking



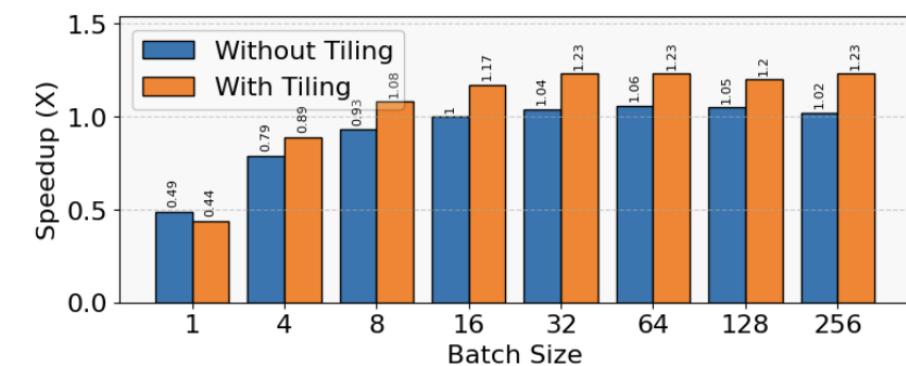
- Diffusion models now generate images nearly **indistinguishable** from real photos.
- Social platforms face **billions** of daily uploads (YouTube, TikTok, Facebook).
- Watermarking is critical for **verifying** AI-generated content and copyright attribution.

# Challenges of Diffusion Watermarking Detection

- Validation accuracy of naive tile-based Stable Signature on different tile size.
- Naive tile-based design brings only limited improvement.

None	128	96	80	64	48	32	16
0.997	0.960	0.933	0.897	0.875	0.804	0.714	0.624

**Challenge-1:** How to balance the trade-off between accuracy and efficiency?



**Challenge-2:** How to optimize the tile-based watermark detection pipeline for higher throughput?

# Motivation from Real-world Observations

**Observation1:** **One tile** of an entire image is **sufficient** for watermark detection.

None

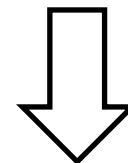


Crop 10%



Accuracy reduction: 99% ->95%  
(even without pretraining on tiles)

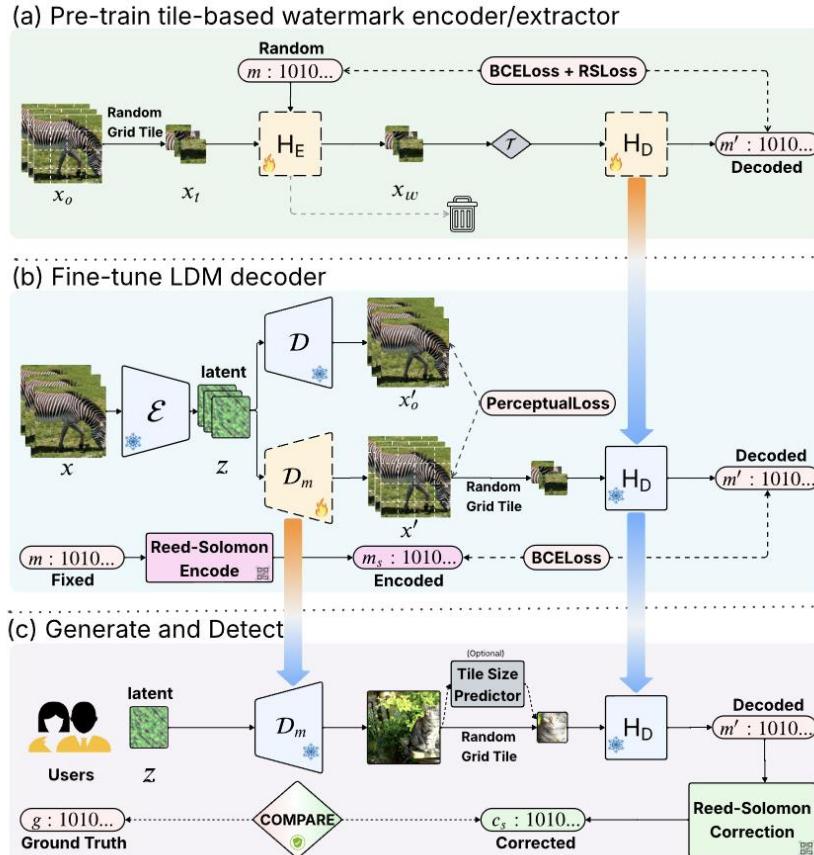
**Observation2:** A QR code can still be **accurately** and **quickly** even when part of it is **missing**.



[https://en.m.wikipedia.org/wiki/Main\\_Page](https://en.m.wikipedia.org/wiki/Main_Page)

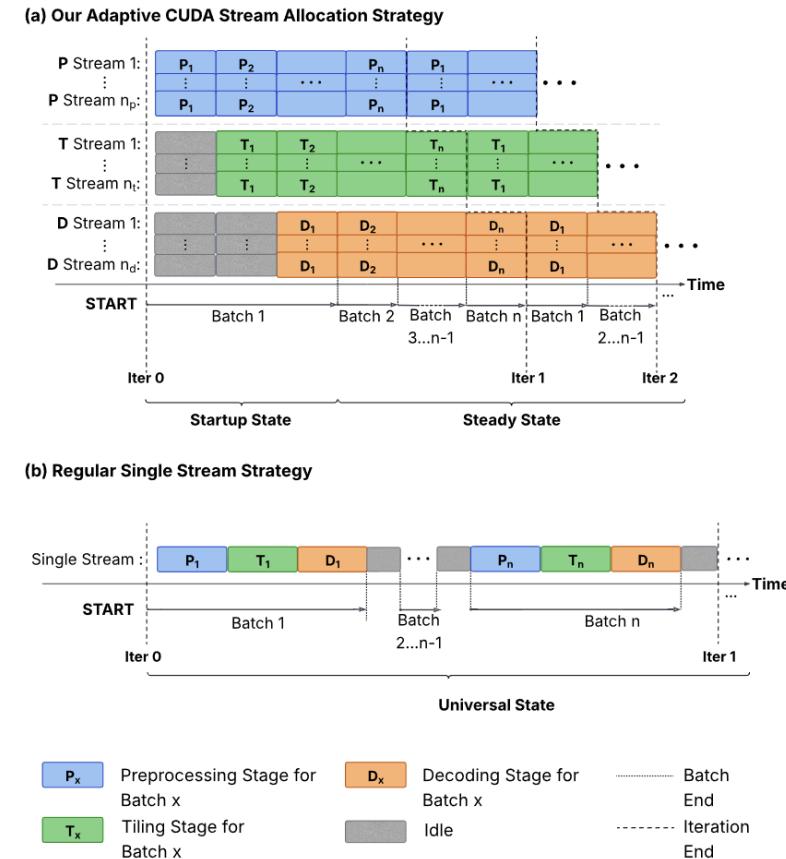
# Algorithmic-System Co-Design Solution

- Tile-based detection with RS Correction



Leverage **RS correction** to offset the accuracy degradation caused by **tiling**

- Adaptively allocate CUDA stream for each stage



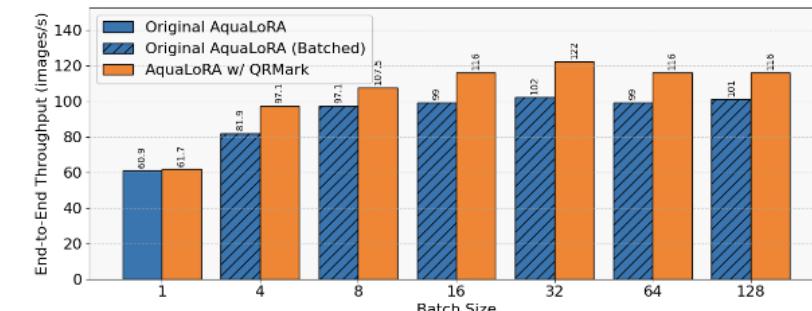
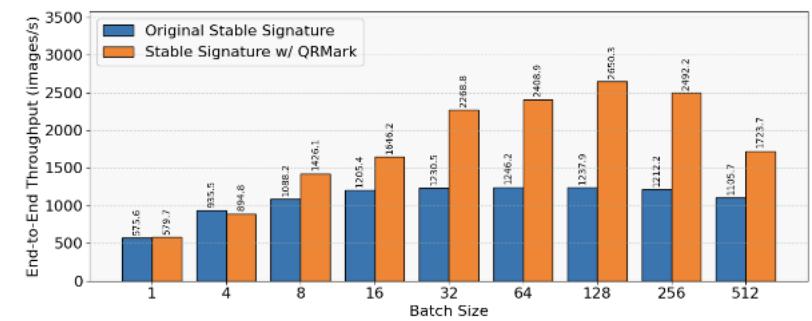
Equalize the **per-minibatch execution** time across stages

# End-to-end Performance

- End-to-end accuracy and robustness

Model	TS	BitAcc. $\uparrow$	BitAcc. (ADV.) $\uparrow$	PSNR $\uparrow$	TPR $\uparrow$
StableQR	16	0.748	0.665	27.67	0.761
	32	0.989	0.907	29.47	0.993
	48	0.997	0.933	29.63	0.996
	64	0.999	0.945	30.35	0.998
	80	0.999	0.949	30.76	0.999
StableBL	—	0.999	0.974	30.05	0.993
AquaLoRAQR	256	0.947	0.883	17.13	0.970
AquaLoRA <sub>BL</sub>	—	0.958	0.912	17.65	0.985

- End-to-end Throughput



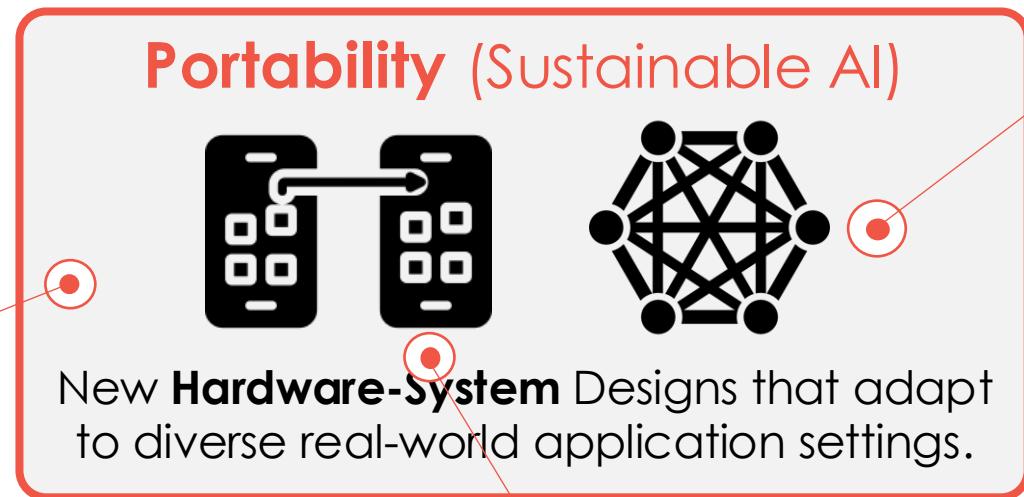
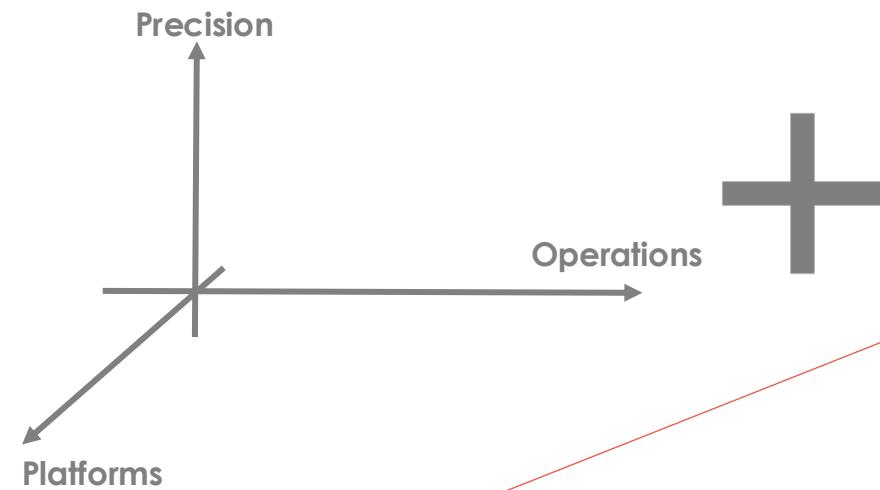
2.20x over Stable Signature [1]  
and 2X over AquaLoRA [2].

[1] Fernandez, Pierre, et al. "The stable signature: Rooting watermarks in latent diffusion models."

Proceedings of the IEEE/CVF International Conference on Computer Vision. 2023.

[2] Feng, Weitao, et al. "Aqualora: Toward white-box protection for customized stable diffusion models via watermark lora." arXiv preprint

# Future Research: New Hardware-System Optimization

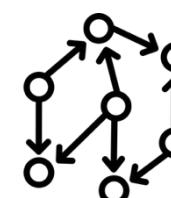


Eco-friendly DL with **Energy/Carbon-aware HW-System Co-Optimization**



- Dynamic Energy Scaling to balance runtime performance and energy cost.
- Carbon-Aware Scheduling to balance energy availability and job requirements.

**Accelerated DL with Reconfigurable Dataflow Architecture (e.g., SambaNova)**

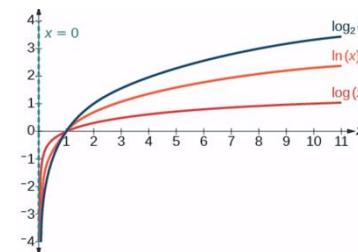
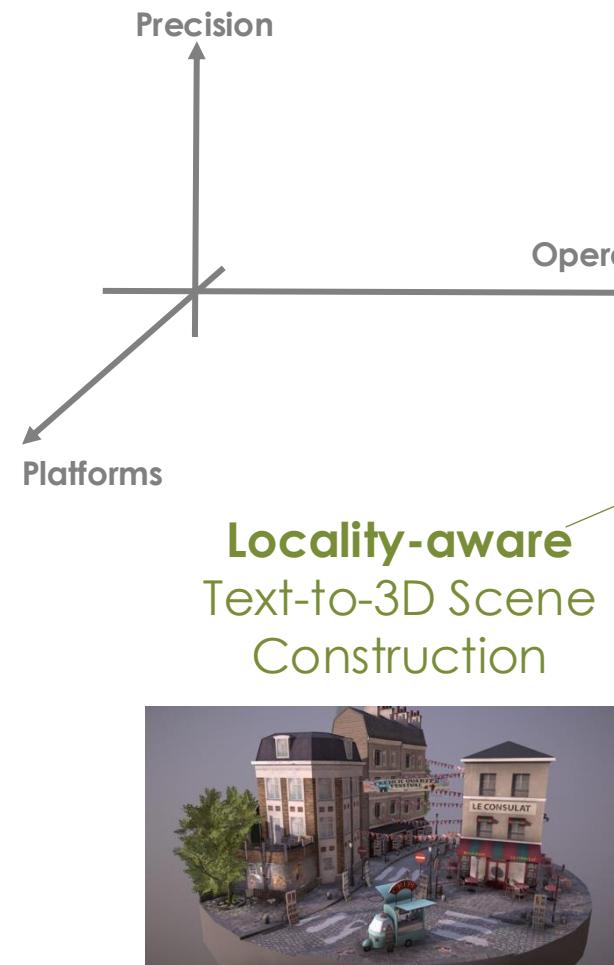


**Efficient DLRM with Disaggregated Memory (e.g., CXL)**

- Co-design/optimization with diverse accelerators.
- Co-scheduling Workloads with Near-data Processing.
- Multi-Tenant Support for co-locating Diverse DL applications.

- Compiler optimization for dataflow design space search.
- Workload-aware Runtime Dataflow Reconfiguration.

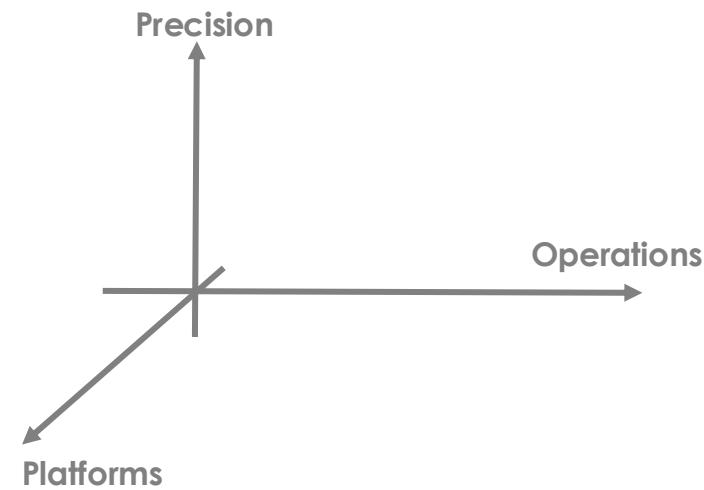
# Future Research: Exploring New DL Workloads



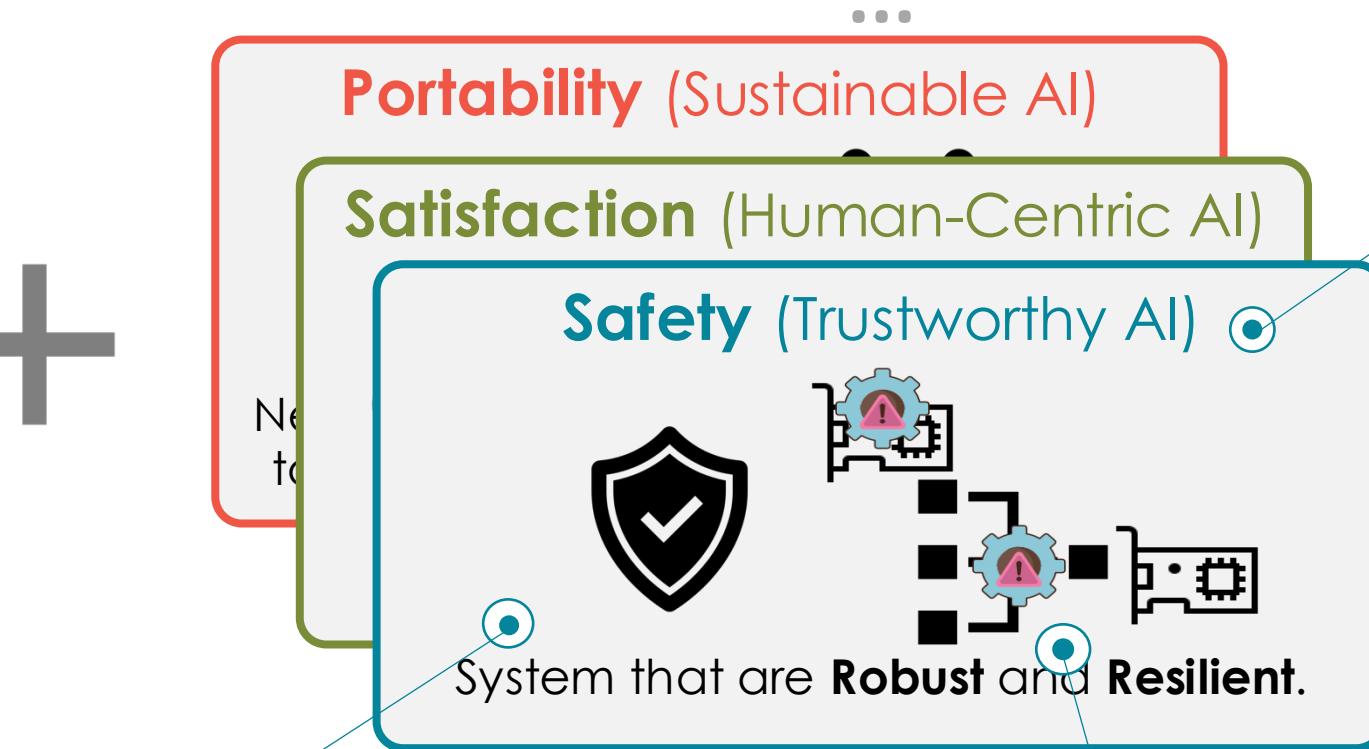
- Cross-iteration spatial and temporal in 360 Panorama rendering and 3D scene lifting.
- Cross device (e.g., multi-GPU platforms) objects artifacts locality.

- Dynamic DL precision with multi-base LNS.
- Memory-efficient model quantization with selective LNS.

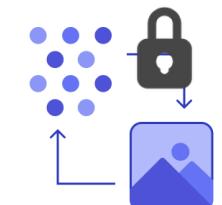
# Future Future: Secure and Resilient DL System



- Failure-resilient routine for heterogenous memory and compute devices.



**Confidential/  
Encrypted  
DL Model  
Serving**



- Holistic scheduling of encryption and regular DL ops for low-cost DL model training.

**Efficient  
Watermarking for  
IP-Protected DL.**

- Robustness-aware Watermarking for efficient real-time processing.



# Thank You

## Q & A

 [yuke.wang@rice.edu](mailto:yuke.wang@rice.edu)

 [github.com/YukeWang96](https://github.com/YukeWang96)

 [wang-yuke.com](http://wang-yuke.com)